



Modelling sea-level fingerprints of glaciated regions with low mantle viscosity

I would not sign, this statement. First, the sea level equation or GRD does this job. The fingerprint describes only the sea-level pattern for a mass redistribution originating from a specific location (see line 41). Furthermore, the formalism can be used for any water mass redistribution between land and sea.

Alan Bartholet¹, Glenn A. Milne¹ and Konstantin Latychev²

¹ Department of Earth and Environmental Science, University of Ottawa, Ottawa, K1N 6N5, Canada

² Department of Earth and Planetary Sciences, Harvard University, Cambridge, MA 02138, USA

Correspondence to: Glenn A. Milne (gamilne@uottawa.ca)

Abstract. Sea-level fingerprints define the spatially varying relative sea-level response to changes in grounded ice distribution.

These fingerprints are a key component in generating regional sea-level projections. Calculation of these fingerprints is commonly based on the assumption that the isostatic response of the Earth is dominantly elastic on century time scales. While this assumption is accurate for regions underlain by mantle material with viscosity close to that of global average estimates, recent work focusing on the West Antarctic region has shown that this assumption can lead to significant error where the viscosity is markedly lower than the typical average values. Here we test this assumption for fingerprints associated with glaciers and ice caps. We compare output from a (1D) elastic Earth model to that of a 3D viscoelastic model which includes low viscosity mantle in three glaciated regions: Alaska, southwestern Canada and the southern Andes (Randolph Glacier Inventory (RGI) regions 1, 2 & 17, respectively). This comparison indicates that the error incurred by ignoring the non-elastic response is generally less than 1 cm over the 21st century but can reach magnitudes of up to several 10s of centimetres in low viscosity areas. This error can have large spatial gradients where crustal uplift in ice covered (or previously ice covered) areas changes into subsidence when moving away from the loading centres to areas peripheral to the mass loss. The existence of these large gradients indicates the need for loading models with high spatial resolution to accurately simulate sea-level fingerprints in these regions. We conclude that sea-level projections for Alaska, southwestern Canada and the southern Andes should not be based on elastic Earth models.

What about more accurate earth structures? See also Klemann et al. 2007. The sensitivity regarding the impact of higher resolved loading models is not discussed in this manuscript.

1 Introduction

which processes

vertical position

of the

check for consistent hyphenation.

A variety of processes drive changes in the height of the ocean floor and ocean surface (e.g. Church et al., 2013; Milne et al., 2009), and the combination of these processes produces a complex pattern of sea level change that varies through time as the relative contribution of each process often changes. While the global average relative sea-level change provides a useful single value which reflects the contribution from climate-related processes, specifically land ice melt and ocean warming, and does represent a good estimate of sea level change at many coastal locations, various regional processes that produce a strong signal can result in large departures from the global average value (Church et al., 2013). As a result, predicting future sea-level changes at regional to local scales is challenging as it requires calculating the signal associated with numerous physical

I would argue the global mean is a suitable measure to quantify the effect of mass and volume changes of the ocean, but it fails at predicting sea-level change at regional to local scales. Also I would introduce the terminology of Gregory et al. 2019 already here.

processes that have a range of spatial scales and response times ~~and then summing the results~~ (Slangen et al., 2011; 2014; Kopp et al., 2014).

Around the world, glaciers and ice sheets are losing mass and retreating (e.g. Oppenheimer et al., 2019; Vaughan et al., 2013; Shepherd et al., 2018; 2020; Wouters et al., 2019; Zemp et al., 2019). Observations since 1850 show that, on a global scale, the rate of glacier mass loss in the early 21st-century is without precedent ~~for the observation period~~ (and potentially for all recorded history) (Zemp et al., 2015). The melting of ice sheets and glaciers produces a ~~complex~~ pattern of sea level change due to the resulting solid Earth deformation and changes ~~to~~ ^{of} the geopotential (Farrell and Clark, 1976). When these changes happen on decadal to centennial time scales the resulting solid Earth response is dominantly elastic ~~and so the non-elastic~~ (viscous) component is commonly ignored. The modelled spatial patterns in relative sea-level change associated with these short-term changes in ice mass are often termed "sea-level fingerprints" (e.g. Mitrovica et al., 2011). These fingerprints play a central role in projections of regional sea-level change (Church et al., 2013; Oppenheimer et al., 2019; Slangen et al., 2012; 2014; Spada, 2017). ~~I would not call it a 'component' but anelasticity and viscous material behaviour of the earth's mantle is neglected.~~

; Palmer et al., 2020, doi:10.1029/2019EF001413

45 The assumption of an insignificant contribution of the ~~non-elastic signal~~ to sea-level fingerprints was recently addressed in a paper focusing on mass loss of the Antarctic ice sheet (Hay et al., 2017). The viscosity of the Earth's mantle is known to be several orders of magnitude lower than ~~that of~~ the global average ~~in this region~~ (e.g. Whitehouse et al., 2019). Hay et al. (2017) concluded that the viscous component of the response is significant and so should be included when computing sea-level fingerprints. In this study, we ~~address the same question but focus on regions with glaciers that are underlain by low viscosity mantle rock.~~ ^{West-} ~~Recent~~ ^{extent this discussion to further} studies have provided evidence that the glaciated regions of Alaska, Western Canada & USA and the Southern Andes are located in regions where the sub-lithosphere mantle viscosity is several orders of magnitude lower than typical global mean values (e.g. Hu and Freymuller, 2019; James et al., 2009; Jin et al., 2017; Richter et al., 2016). The cause of such low viscosity is ~~believed to be~~ related to the presence of plate subduction in these areas. Departure from an elastic response will be relatively large in these regions and so the computed sea-level fingerprints may be in significant error. The primary aim of this work is to quantify the amplitude and spatial extent of the error caused by assuming an elastic Earth response in the three regions mentioned above. In particular, a key goal is to determine if the influence of these low viscosity regions extends significantly beyond the regions defined by low viscosity mantle material.

2 Methods

Our sea-level projections were generated using a numerical finite-volume formulation of the surface loading process (e.g. Latychev et al., 2005; Hay et al., 2017). This formulation assumes a spherical Maxwell body, filled by tetrahedral elements in which the lateral resolution is greatest (~12 km) near the surface of the Earth model and lowest (~50 km) at the core-mantle boundary. Immediately beneath the surface, the depth resolution is ~12 km, compared to ~50 km immediately above the core-

Can be written more precisely: A Maxwell body is a rheological law, the tetrahedral elements are discretising the continuum. What means 12 km near the surface, how deep do they extent in this resolution. The tetrahedral elements are symmetric? Then the description of the depth resolution is redundant as it corresponds to the lateral resolution.



to solve the sea-level equation

Glacial isostatic
 adjustment

I think, for the time scale considered the
 theory will not deviate from Farrell and Clark

mantle boundary. The ~~sea-level~~ algorithm used in our **GIA** model is based on ~~the theory described in~~ Mitrovica and Milne
 (2003) and described in Kendall et al. (2005) but extended to incorporate the influence of Earth rotation on RSL changes
 65 (Milne and Mitrovica, 1998; Mitrovica et al., 2005). In order to apply this algorithm, two primary inputs must be defined: a
 realistic space-time evolution of grounded land ice to force the model and a realistic model of the Earth that defines the interior
 density and rheology structure to compute the ~~isostatic~~ ^{viscoelastic} response. These two model inputs are detailed below.

2.1 Ice model

In this study we created ice models for each of the 19 first order regions in the Randolph Glacier Inventory 5.0 (RGI; Pfeffer
 70 et al., 2014). The RGI provides the area of glacier extent in each of the regions and then we apply the region-specific thickness-
 area scaling function of Huss and Farinotti (2012) which calculates the mean thickness of each glacier in a region using:

Care about the font in the text which seems to
 be bold here.

$$\bar{h} = cS^\gamma \quad (1)$$

where **\bar{h}** is the mean thickness, **S** is the area of the glacier, and **c** and **γ** are constants specific to each region in the RGI. In
 order to determine a mass loss history for our ice model for all 19 regions in the RGI we use the decadal Representative
 75 Concentration Pathway (RCP) 4.5 projections provided by Huss and Hock (2015) for the period 2010-2100 CE with a net
 global ^{mean} barystatic (Gregory et al., 2019) sea-level change of 10.8 cm.

I guess the RCP projection is aggregating the impact of
 all glaciers.

Using the decadal mass loss projections we produced a model of ice extent changes that simulates the vertical thinning of the
 ? GICs as well as a crude estimate of lateral retreat as the area of ice cover changes. We iterated over each of the decadal time
 80 steps and calculated the amount of uniform ice thickness change (based on areal extent) required to equal the projected sea-
 level equivalent (SLE) using a tolerance of $\pm 1\%$. We then subtracted this height from the ice thickness distribution of the
 previous time step and revised the area distribution to account for locations where ice thickness had reduced to zero. We then
 applied a spatial Gaussian filter to the calculated change in ice extent between successive time steps (using NumPy 1.16.1
 Multidimensional Gaussian filter) to spatially smooth the ice thickness distribution. While this did result in some loss of spatial
 85 fidelity, it removed large spatial gradients in the ice thickness distribution that were unphysical. This process was applied
 individually to each of the 19 first order regions in the RGI. Figure 1a shows ice extent at 2010 and 2100 CE for the RGI
 regions 1 (Alaska) & 2 (Western Canada and USA) and Figure 1b gives the same results for region 17 (Southern Andes).

characteristics of the filter applied are missing, e.g. the filter width.

how these can be unphysical?

I am a bit puzzled. In your conclusions you state, the we have to increase the accuracy of
 the loading, but, here you apply a spatial filtering, which somehow removes some details. If the
 glacial inventory contains or generates some artefacts you should discuss those.

2.2 Earth model

The density and elastic properties of our Earth model are defined using the radial (1D) seismic Preliminary Reference Earth
 90 Model (Dziewonski and Anderson, 1981). We note that the influence of lateral variations in elastic and density structure on
 the computation of sea-level fingerprints has been shown to be negligible (Mitrovica et al., 2011). Due to large uncertainty in
 our knowledge of the viscosity structure of the Earth, the viscosity structure is most commonly defined by only three
 parameters: the first is an outer shell of high viscosity (1×10^{37} Pa s) which is used to simulate an elastic outer shell (the



that the mean
earth response is elastic, and, so the viscosity structure does not affect the

lithosphere); the second is an isoviscous upper mantle region which extends from the base of the lithosphere to a depth of 670 km; and third, an isoviscous lower mantle region that extends from 670 km to the core-mantle boundary (2885 km). The values used to define the viscosity vary depending on the region detailed below resulting in an Earth model where the internal viscosity structure varies not only with depth but laterally as well. In contrast, the surface features of the Earth model (e.g., ice extent, topography) vary as a function of time and geographic position. This statement is rather redundant here.

In defining global-scale viscosity structure, we assign a lithospheric thickness of 96 km, an upper-mantle viscosity of 5×10^{20} Pa s, and a lower-mantle viscosity of 1×10^{22} Pa s. While there is considerable uncertainty in our knowledge of global average viscosity structure, the majority of this uncertainty relates to that of the lower mantle (e.g. Mitrovica and Forte, 2004; Lambeck et al., 2014). The values we use for lithospheric thickness and upper mantle viscosity are broadly compatible with those from recent analyses of global GIA data sets (Lambeck et al., 2014; Peltier, 2004) and the value we use for lower mantle viscosity represents a middle ground between these recent estimates. Given short time period of our model simulation (~ 100 yr), the use of other global average viscosity structures could be substituted without significantly impacting the results as the component of non-elastic deformation is small for viscosity values typically inferred in global GIA analyses. The regional viscosity structure we adopt is the more important aspect of our Earth model as this is anomalously low in RGI regions 1, 2 & 17. The question then would be why the mean earth is not considered as elastic?

For RGI region 1 (Alaska), a number of studies have estimated the regional viscosity structure (e.g. Larsen et al., 2005; Sato et al., 2011; Jin et al., 2017; Hu and Freymueller, 2019). All of these studies estimate a relatively thin lithosphere elastic thickness, averaging around 50 km but with uncertainty of a few 10s of km, and low viscosity values in the shallow upper mantle ranging between middle 10^{18} Pa s to low 10^{19} Pa s. In a relatively recent analysis, Jin et al. (2017) used measurements from Ice Cloud and Land Elevation Satellite (ICESat), global positioning system (GPS), and Gravity Recovery and Climate Experiment (GRACE) to estimate a number of ice and Earth model parameters. By isolating the signal due to past ice loading, they concluded on a best fit three-layer Earth model consisting of a lithospheric (elastic) thickness of 60 km, a 110 km thick asthenosphere with a viscosity of 2×10^{19} Pa s, and a sub-asthenosphere mantle with a viscosity of 4×10^{20} Pa s. A more recent study (Hu and Freymueller, 2019) also used vertical land motion rates from GPS to constrain regional, depth-dependent viscosity structure. They estimated lithosphere thickness to be 55 km and the viscosity and thickness of the asthenosphere to be, respectively, 3×10^{19} Pa s and 230 km, but noted the significant trade-off in these parameter values.

Thicker asthenosphere results in larger viscosity I guess.

While there is a considerable degree of uncertainty in defining model parameters for this region, the relatively good agreement between these two recent studies gives some confidence in choosing parameters. We adopted the values of Jin et al. (2017) for this study (those from Hu and Freymueller (2019) were published after the completion of our modelling) and extended their sub-asthenosphere region (with a viscosity of 4×10^{20} Pa s) to the bottom of the upper mantle (670 km); below this depth values associated with the global background model are the default. The lateral extent of these viscosity values at the model Earth surface is shown in red in Figure 2a. In order to constrain the lateral extent of the low viscosity region we define a surface

this can be shortened,,stating the considered structure is based on Jin et al. with[...] A more recent study by Hu and Freymueller [...], which was published after finishing the modelling in this study, show similar results [...].



area that is roughly similar to the region studied by Jin et al. (2017). Note that the extent of this region decreases with depth to ensure that the proportion of this region relative to the global area at a given depth remains constant. **So, you project it down in radial direction?**

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For RGI region 2 (Western Canada & USA), we are interested only in the area adjacent to southwestern British Columbia as this is where GIA studies have inferred low viscosity values: James et al. (2009) concluded that RSL observations from Vancouver Island can be fit equally well across a wide range of asthenosphere thicknesses and viscosities. The Earth model with the lowest viscosity consisted of a lithospheric (elastic) thickness of 60 km, a 140 km thick asthenosphere with a viscosity of 3×10^{18} Pa s, and a sub-asthenosphere mantle with a viscosity of 4×10^{20} Pa s. These results are supported by a more recent study that considered sea-level observations from a larger area in southwestern British Columbia (Yousefi et al., 2018) and so we adopt the values from James et al. (2009) to define the regional lithosphere thickness and upper mantle structure. The lateral extent of this region at the model Earth surface is shown in green in Figure 2a.

135

140 In the southern Andes region (RGI area 17), a number of studies have inferred the presence of low viscosity mantle rock (e.g. Ivins and James, 1999; Ivins and James, 2004; Lange et al., 2014; Richter et al., 2016) that likely resides in the mantle wedge between the subducting plate and the base of the lithosphere (Klemann et al., 2007). In all of these studies, the estimated lithosphere elastic thickness is relatively thin (~30 km) and asthenosphere viscosity low (order 10^{18} Pa s). We adopted results from the most recent of the above-listed analyses, Richter et al. (2016), who used observations from 43 geodetic Global Navigation Satellite System (GNSS) sites distributed over the Southern Patagonian Ice Field to analyze vertical and horizontal velocities of present-day crustal deformation. By applying an ice-load history that assumes a moderate present-day glacial mass loss, with slightly higher than present-day mass loss immediately following the Little Ice Age (LIA) maximum, Richter et al. concluded on a preferred Earth model consisting of a 36.5 km thick lithosphere and a sub-lithosphere mantle with a viscosity of 1.6×10^{18} Pa s. The lateral extent of these viscosity values at the model Earth surface is shown in red in Figure 2b. **To which depth do you extend this low viscosity region?**

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3 Results and Discussion

Our goal is to quantify the signal of the non-elastic response to sea-level fingerprints computed for the three RGI regions introduced above. Therefore, in the following, we compare results from our 3-D viscoelastic Earth model to those computed assuming the Earth response to the loading changes is elastic. **Why do you not compare it also to a 1D viscoelastic model?**

155

Figure 3a shows the global sea-level fingerprint for the non-linear mass loss results of Huss and Hock (2012) as applied to all regions of the RGI assuming Earth deformation is entirely elastic. As is conventional, the fingerprint shows the total sea level change between the start and end of the study period (in this case, 2010 to 2020 CE). The pattern of sea-level change is typical in that it shows a sea level fall near the sources of the ice mass loss and a sea level rise in the far-field (e.g. Mitrovica et al.,



That would be $1-2 \text{ cm} / 100 \text{ yr} = 0.1-0.2 \text{ mm/yr}$ which is not observable by current observation systems.

This statement is redundant. Anyhow one should show the difference.

2001). Using the same ice loading model, results for the 3D viscoelastic Earth model are shown in Fig. 3b. At the global scale, comparison between the results in Figs 3a & 3b shows that the differences are small; therefore, we subtract the elastic results from the viscoelastic results (Fig. 3c) to isolate the difference. In Figure 3c, at locations on the order of 1000 km or more away from the ice load, the difference between the viscoelastic and elastic Earth models is negligible (less than 1 cm at 2100 CE). Nevertheless, this is a signal. Does it also appear in case of a 1D ve earth? At locations peripheral to glaciated region, the difference is generally within a few cm, with the largest differences evident in the areas underlain by low viscosity mantle material. In glaciated regions where the viscosity structure is that of the global model (i.e. all RGI regions except 1, 2 & 17), there is a difference of 1-2 cm between the elastic and viscoelastic results indicating that the assumption of an elastic Earth is relatively accurate even in near-field regions when the viscosity of underlying mantle is close to global average values. However, at locations inside the boundaries depicted in Figure 2 (the “near-field”), the difference in sea-level change can be several times larger than the global mean barystatic value (10.8 cm) due to the faster response times of the low viscosity mantle. Thus, the error introduced by considering only the elastic solid Earth response is spatially restricted and reaches the several cm level only in the vicinity of the low viscosity regions. The remainder of this section will focus on the signal in these near-field regions only. This is a very important result.

Sea-level predictions for the elastic and viscoelastic Earth models, as well as the difference between them, for the regions with underlying low viscosity mantle are shown in Figure 4. A map showing the results for Alaska and Western Canada & USA (Figure 4a-c) indicates that the spatial pattern associated with the viscoelastic signal is markedly different than that for the elastic Earth model. Note that, for ease of interpretation, the predictions shown in Figure 4 consider only the RSL change associated with ice mass loss in the respective RGI regions (1, 2 in Fig. 4a-c and 17 in Fig. 4d-f), hence the difference between the results in Figs 3 & 4. The influence of ice changes in other RGI regions will cause an almost uniform signal over each of the areas shown in Fig. 4, with amplitude close to the global barystatic value, and so the spatial patterns (gradients) will not be significantly affected by this omission. Furthermore you should mention that the difference between elastic and viscoelastic results in less than a cm difference.

Inspection of Fig. 4 indicates that the spatial pattern associated with the viscoelastic signal is markedly different to that of the elastic Earth model. In particular, when an elastic model is used, the near-field RSL signal is entirely negative reflecting subsidence of the geoid (dominated by ice mass loss) and uplift of the solid Earth. In the viscoelastic case, when there is sufficient time for the non-elastic component of deformation to become significant, a zone of solid Earth subsidence peripheral to the ice covered region becomes apparent, particularly in RGI region 1. These so-called ‘peripheral bulges’ are a characteristic feature of the GIA response on millennial time scales (e.g. Peltier, 1974; Clark et al., 1978; Whitehouse et al., 2018) and reflect the isostatic signal of a thin elastic lithosphere overlying a viscoelastic mantle within which the non-elastic component of deformation is significant (i.e. close to or exceeding the Maxwell time of the deforming material).

Focusing first on the results for RGI regions 1 & 2 (Fig. 4a-c), in areas where ice has thinned or disappeared (Fig. 1), the RSL change is less than that of the elastic case whereas peripheral to this area, the RSL change is greater. This pattern is somewhat



- intuitive when one considers the peripheral bulge effect noted above and the faster response time of the low viscosity material.
- 195 Because of the considerably lower mantle viscosity in these regions, the solid Earth responds faster than it otherwise would have over the same time period. As a result, the areas shaded in red show a greater sea level fall compared to the elastic case due to the additional uplift of the solid Earth surface associated with non-elastic deformation. The peripheral areas showing an enhanced sea-level rise (blue colour in Fig. 4a) relate to deformation associated with the peripheral bulge. In these peripheral areas, solid surface uplift occurs during loading followed by subsidence once unloading becomes dominant. Thus, the predicted sea-level fall is related to subsidence of the peripheral bulge that is active following the onset of sustained ice mass loss. The error made by assuming an elastic Earth response can exceed several 10s of cm and be positive or negative depending on location relative to the transition from uplift to subsidence (red to blue colour in Fig. 4). Of note are the large gradients in the RSL response when transitioning between uplifting and subsiding regions.
- 200 Not clear I am a bit puzzled in which peripheral area you are now. On line 199, you discuss a sea-level rise.
- 205 The above interpretation assumes that the differences in RSL are dominated by changes in vertical land motion rather than in sea-surface height (due to gravitational changes associated with the Earth deformation). Model output of vertical land motion and sea-surface height change, support this interpretation and show that the sea surface component is, in general, smaller than the land motion signal but this is site and time dependent (see Fig. 5 and related discussion below).
- 210 Results for the Southern Andes (Figure 4d-f) are similar in that the non-elastic component of deformation in this region results in a more rapid sea-level fall in areas of ice thinning/retreat. The RSL differences (compared to the elastic case) are not as large as for RGI region 1 as the amplitude of mass loss is less (Fig. 1), but the differences still reach values of up to 10s of cm and so are large. The influence of the peripheral bulge is more subtle than for RGI region 1. This is due to the different amplitude and geometry of ice mass loss (Fig. 1) and the difference in the viscosity structure of the asthenosphere and upper mantle in the regional Earth models. In the model for Alaska, the viscosity model includes a relatively thin (110 km) low viscosity asthenosphere overlying an upper mantle with viscosity close to that of the global average. In comparison, the regional model for the Southern Andes do not differentiate between the asthenosphere and upper mantle and so a low viscosity is defined from the base of the lithosphere to the bottom of the upper mantle. The more restricted depth extent of the low viscosity region for Alaska would lead to a stronger component of lateral (channel) flow which would affect the amplitude and spatial extent of the peripheral bulge.
- 215 But the assumption of such a deep asthenosphere is rather unrealistic.
- 220

The spatial patterns shown in Fig. 4 are complemented by model output of time series for six different towns or cities (population ranging from ~10,000 to several million inhabitants) in Fig. 5. These particular locations were chosen to illustrate the range of RSL signals evident in these near-field areas. RSL time series for RGI regions 1 & 2 are shown for Juneau and Sitka (Region 1), Vancouver and Victoria (Region 2), and Puerto Natales and Río Grande (Region 17). Time series for both the elastic and viscoelastic cases are based on a 10-year discretization of the ice thickness model as described in Section 2.1. At Juneau, USA, a sea-level fall is predicted for both the elastic (solid green line) and viscoelastic (solid red line) with the



not explained

latter showing a significantly greater fall (by ~ 74 cm). The dashed and dash-dotted red lines show the component signals for the viscoelastic case and these indicate that the vertical land motion (VLM) component dominates over SSH change at this site. Thus, the application of an elastic Earth model greatly underpredicts the sea-level fall at this location. The predicted RSL curves for Puerto Natales are similar in that a sea-level fall is also shown; the amplitude is significantly smaller, however, reflecting the smaller ice mass change in this region and the location of the settlement relative to the area of mass loss, with the viscoelastic case exceeding the elastic by only 4-5 cm.

changes

At Sitka, Vancouver, Victoria and Río Grande, results for the viscoelastic Earth model give an RSL response that ~~transitions~~ from a fall to a rise. This is due to the more complex spatial pattern of the predicted response when a viscoelastic Earth model is applied that has an overlying elastic lithosphere. As noted above, the GIA response is characterised by regions of uplift and subsidence and the so-called “hinge line” that separates these regions. Over the modelled period, the hinge line will migrate towards the main centre of loading over time as the ice retreats and the area of ice cover diminishes. All of these sites are located near the hinge line and so the RSL response transitions from a fall (uplift) to a rise (subsidence) during the 21st century. Looking at the results for these four locations, the non-monotonic nature of the RSL response is governed by that of the VLM; the SSH contribution is primarily that of a sea-level fall associated with the reduction in ice mass resulting in a diminishing gravitational pull on the surrounding ocean. This fall in SSH offsets some of the sea-level rise caused by the VLM in these locations. The non-monotonic shape of the RSL curve has the net effect of resulting in a relatively small RSL change over the 21st century – at all four sites, the amplitude of RSL change is no more than a few cm. As a consequence, the final difference between the elastic and viscoelastic curves at 2100 CE is also relatively small, except in Sitka where the ~~a~~ RSL rise of ~ 4 cm for the viscoelastic model compares to a large fall of ~ 22 cm for the elastic case.

The results shown in Figs 4 & 5 demonstrate that non-elastic deformation can lead to a near-field RSL signal of up to 10s of cm depending on the site location and the magnitude and distribution of regional ice mass loss. In all cases, the elastic model predicts a RSL fall due to the regional ice mass loss, whereas a sea-level rise can result in some localities when the non-elastic signal is considered (e.g. Sitka, Victoria). The large spatial gradients in the predicted viscoelastic RSL response reflects the short wavelengths in the surface load and the thin lithosphere in these tectonically active regions. Given this, the application of a global-scale model, with limited spatial resolution, is not an optimal approach to determine accurate predictions of future RSL change in these near-field regions. As a result of the limited spatial resolution of our model, Iceland, which is known to be underlain by low viscosity mantle, was not included in the analysis. Further work should focus on the use of global models with non-uniform grids (e.g. Larour et al, 2017) or nested, high-resolution regional grids (e.g. Goldburgh et al., 2016) to more precisely define the radial and lateral boundaries of the low viscosity regions as well as the ice extent model. Additionally, in regions where subduction is occurring it may be beneficial to explicitly incorporate the geometry of the subducting plate into the model (e.g. Austermann et al., 2013), rather than the simpler 1-D profiles adopted here.

Klemann et al., 2007.



But you showed that the fingerprint is only different in regions near to the ice unloading coinciding with low viscous regions. I would conclude, that the global fingerprint is not affected by these regional features.

The large amplitude of the non-elastic signal on century time scales in low viscosity regions indicates that application of an elastic model can result in significant error in the calculated sea-level fingerprint. A second important implication of this result is that the isostatic response to the large mass loss changes of the 20th century will be considerable and perhaps a dominant contributor to the RSL response during the 21st century. The importance of this earlier loading signal is evident in the large contemporary uplift rates measured in the regions considered (e.g. Huy and Freymueller, 2019; Richter et al., 2016). We note that this signal is generally not captured accurately in the global scale GIA models most commonly used in generating regional sea-level projections (e.g. Slangen et al., 2014),... which is ok as long as the regions are away from RGI regions 1, 2, 17.

270 While this study assumes a Maxwell rheology, it is possible that, on the relatively short time scales considered here, significant departures from this relatively simple rheological model may occur. These departures could take the form of a transient component of the non-elastic response (e.g. Yuen et al., 1986; Pollitz, 2005), in which the viscosity increases with time or a power-law response that is often associated with relatively large deviatoric stress (e.g. Wu and Wang, 2008; Van de Wal et al., 2013) for which the effective viscosity would increase as stress levels relax. The significance of these more complex
275 rheological models in low viscosity regions would be a natural extension of this analysis.

and what about a feedback to the ice dynamics at marine terminating ice sheets? See Barletta et al 2018 doi:10.1126/science.aao1447.

4 Conclusions

Sea-level fingerprints are an integral aspect of calculating regional variations in future sea-level change. Calculation of these fingerprints commonly assumes that the isostatic response of the Earth is elastic on century time scales. Here we tested this assumption by comparing output from a (1D) elastic Earth model to that of a 3D viscosity elastic model which includes low
280 viscosity mantle in three glaciated regions: Alaska, southwestern Canada and the southern Andes (RGI regions 1, 2 & 17, respectively). This comparison indicates that the error incurred by ignoring the non-elastic response is generally less than 1 cm over the 21st century (but can exceed this in some RGI regions) but can reach magnitudes of up to several 10s of centimetres when proximal (less than ~1000 km) to the three low viscosity areas. This error can have large spatial gradients where crustal uplift in ice covered (or previously ice covered) areas changes into subsidence when moving away from the loading centres to
285 areas peripheral to the mass loss. The existence of these large gradients indicates the need for loading models with high spatial resolution to accurately simulate sea-level fingerprints in these regions. We conclude that sea-level projections for Alaska, southwestern Canada and the southern Andes should not be based on elastic Earth models. Also, the low mantle viscosity in these regions will result in glacier changes during the 20th century dominating the GIA signal and so it is critical that the recent mass loading history (past few centuries) is captured in GIA models applied to estimate future sea-level change in these areas.
290 The impact of low Earth viscosity in these three regions has clear implications for the estimation of sea-level hazard and thus policy decisions on coastal management procedures.

This statement I would not support. At most you can state that LVZ have implications for sea-level hazard in these regions. In contrast, you show that the impact for global sea level is negligible.

This you did not show. Especially in the Andes, the glaciation model considered by Richter et al. extended back to the little ice age, in order to explain the observed GIA signal.



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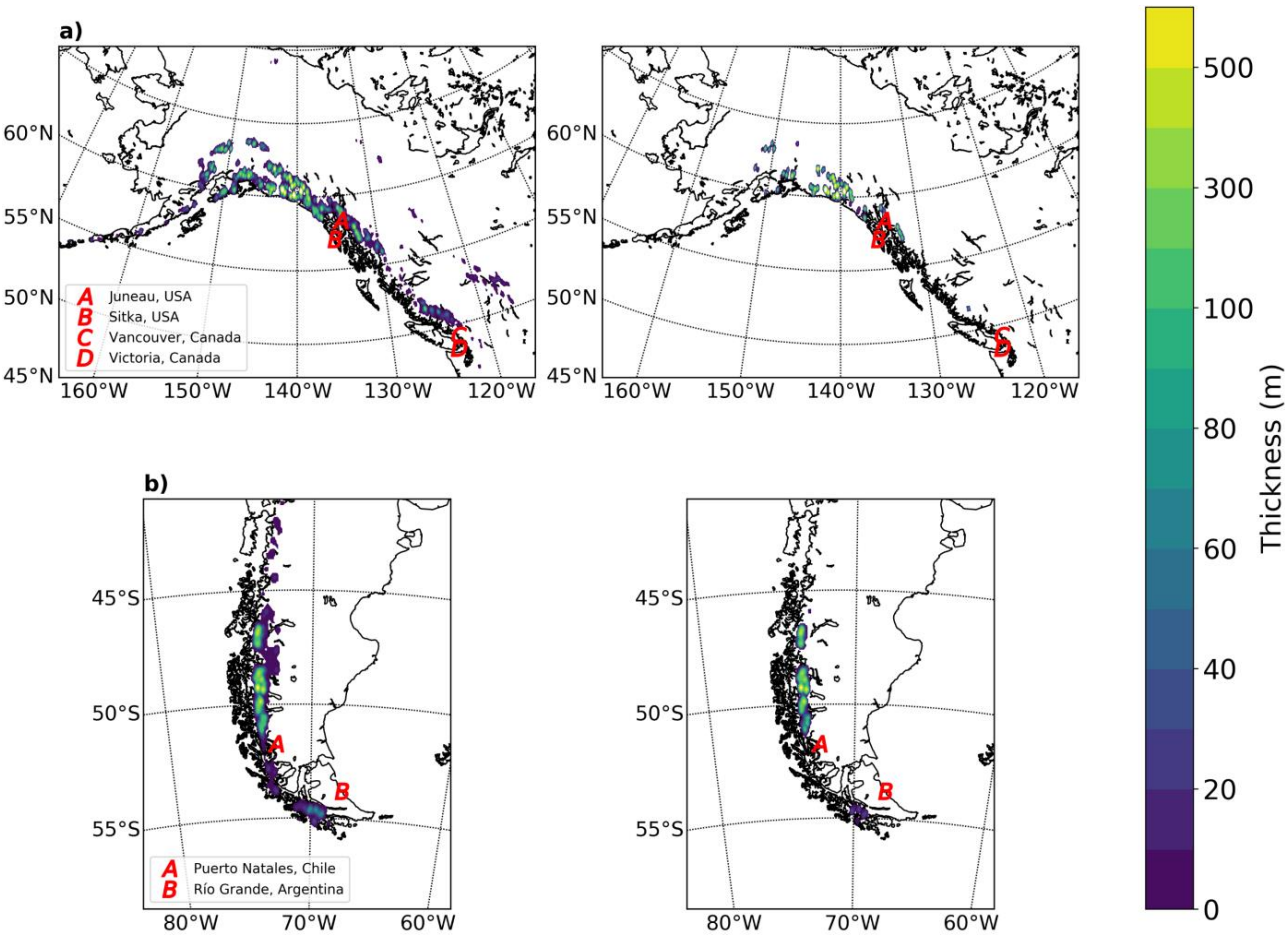


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425

I would use an arrow to point to the respective locations A to D.

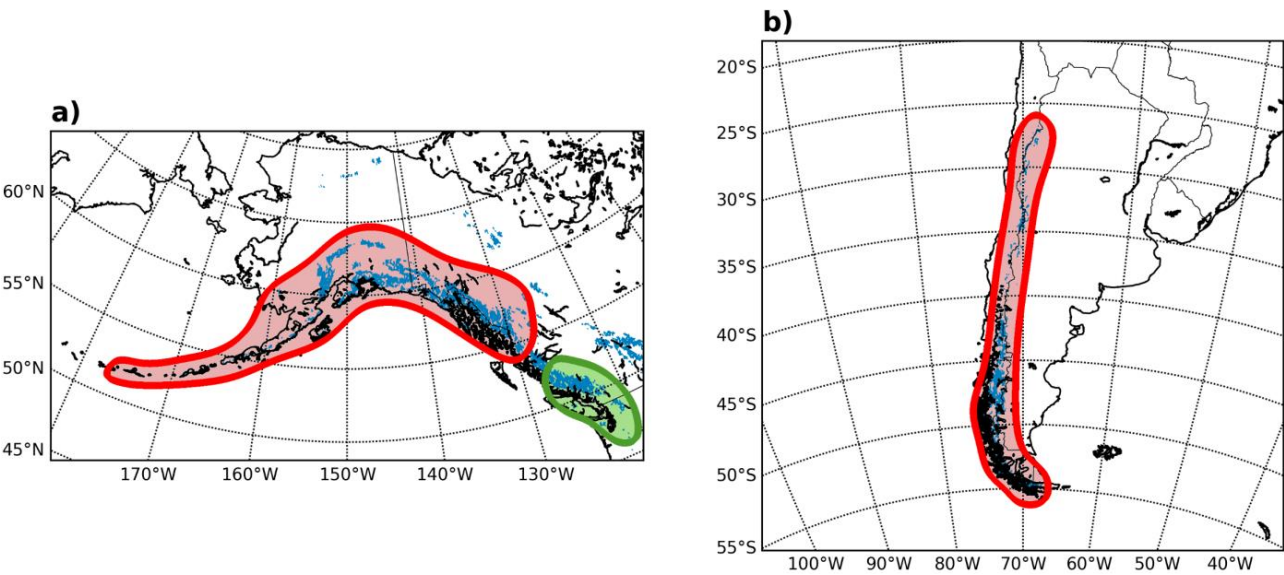


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Figure 1. Estimated spatial distribution in ice thickness in RGI regions 1 & 2 (a) and 17 (b) at the beginning (2010 CE, left) and end (2090 CE, right) of the time period considered. The locations of population centres for which relative sea-level curves are calculated (see Fig. 5) are indicated by the red letters.



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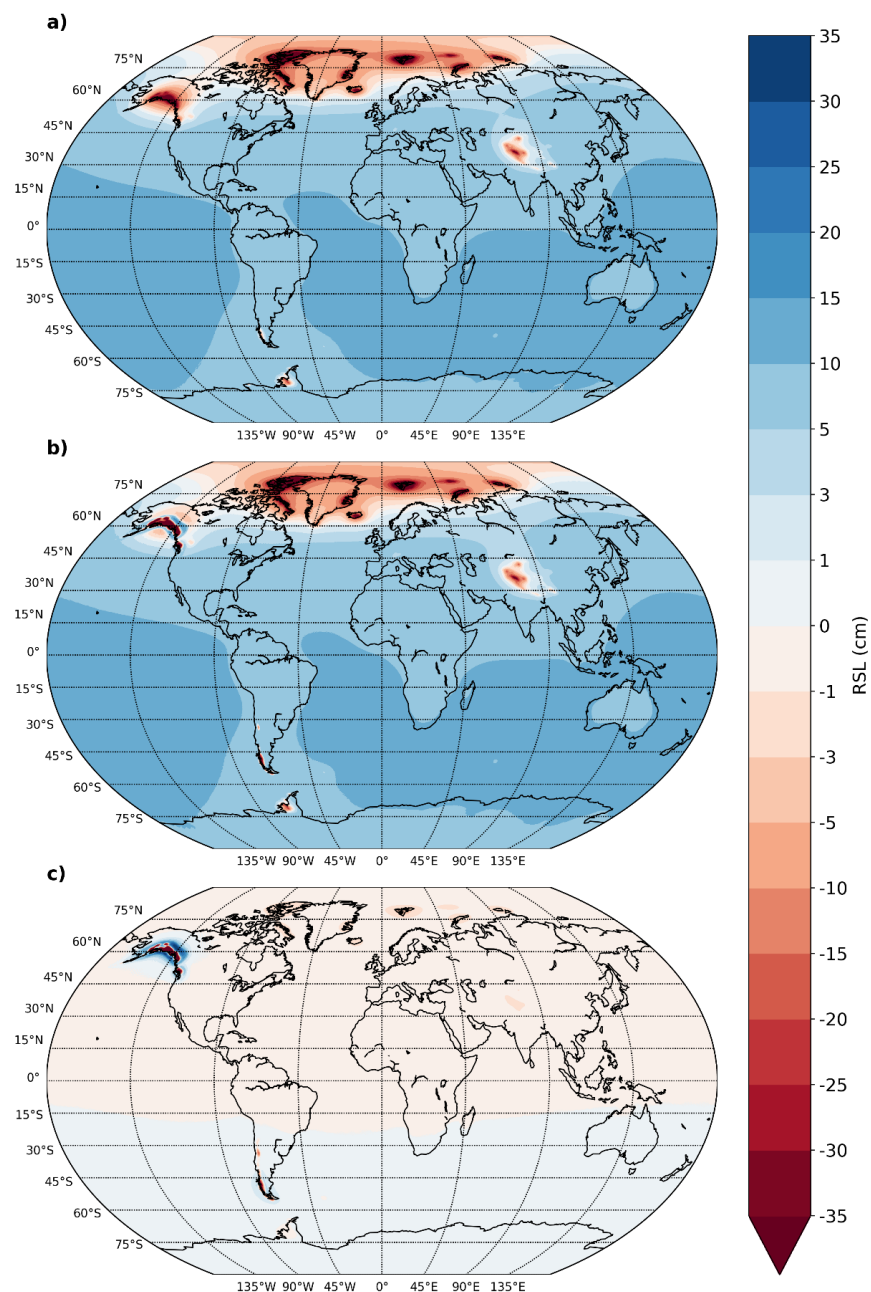


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What are the bluish pattern?

Figure 2. Surface lateral extent of the regions for which the underlying Earth structure (lithospheric thickness and sub-lithosphere viscosity profile) deviate from the adopted global values: (a) shows the extent for RGI regions 1 (red) and 2 (green) while frame (b) shows the extent for region 17.

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Figure 3. Calculated sea-level fingerprints for estimated changes in global glacier distribution from 2010 to 2100 CE for: (a) a 1-D (spherically symmetric) elastic Earth model and (b) a 3-D viscoelastic Earth model with low viscosity regions located as indicated in Fig. 2. (c) The difference between the viscoelastic and elastic results (i.e. (b) minus (a)).



Interestingly the change from RSL fall to rise in the farfield is hardly affected by viscoelasticity.

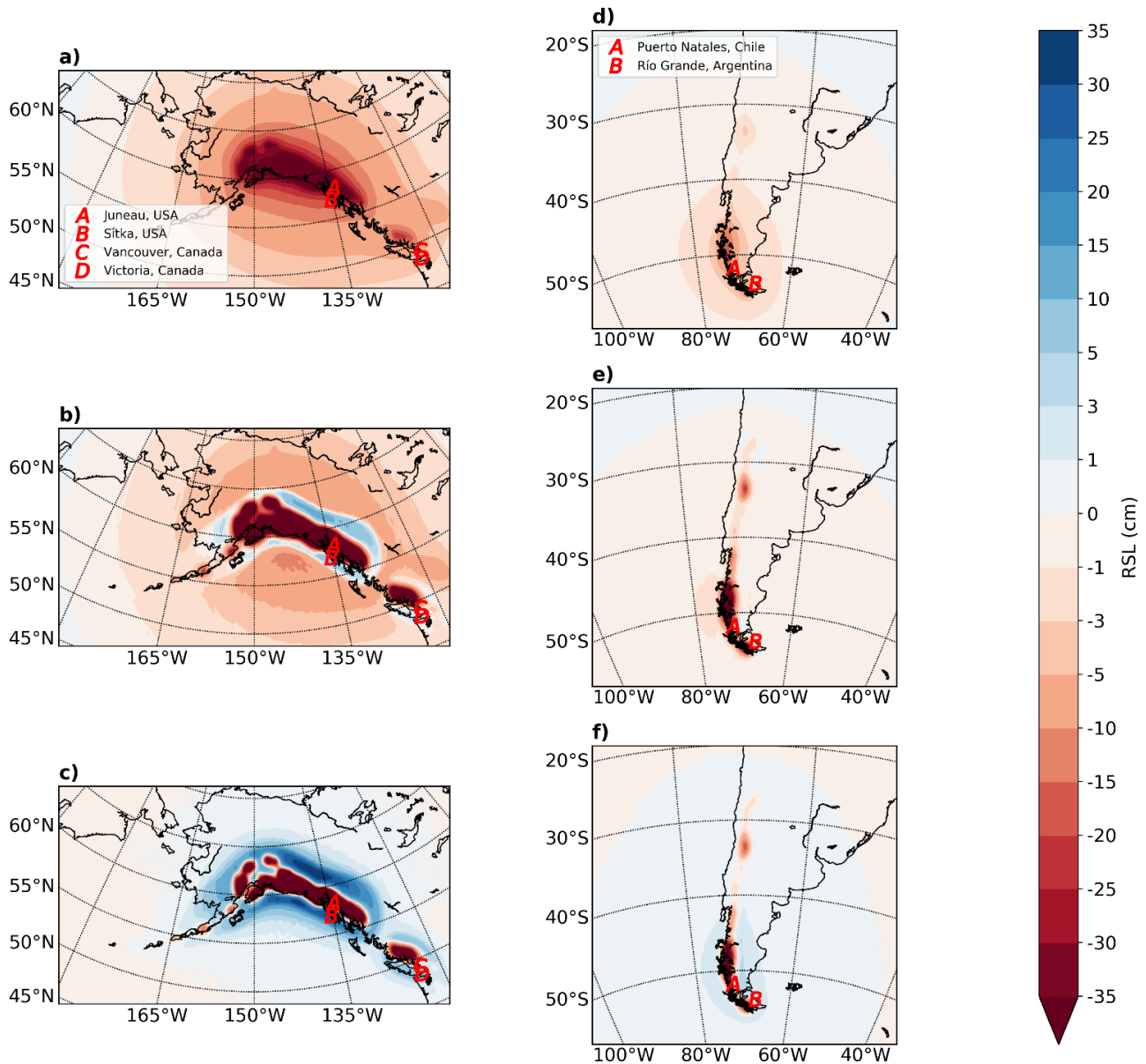


Figure 4. Calculated sea-level fingerprints for estimated changes in regional glacier distributions for RGI regions 1 & 2 (left) and region 17 (right). The different frames show results for: (a & c) a 1-D (spherically symmetric) elastic Earth model, (b & d), a 3-D viscoelastic Earth model with low viscosity regions located as indicated in Fig. 2. The results in (c) and (f) show the differences between the elastic and viscoelastic results, respectively (i.e. (b) minus (a) and (d) minus (e)). Note that these results do not include the sea-level signal associated with ice mass changes from outside of the RGI regions shown. The locations of population centres for which relative sea-level curves are calculated (see Fig. 5) are indicated by the red letters.



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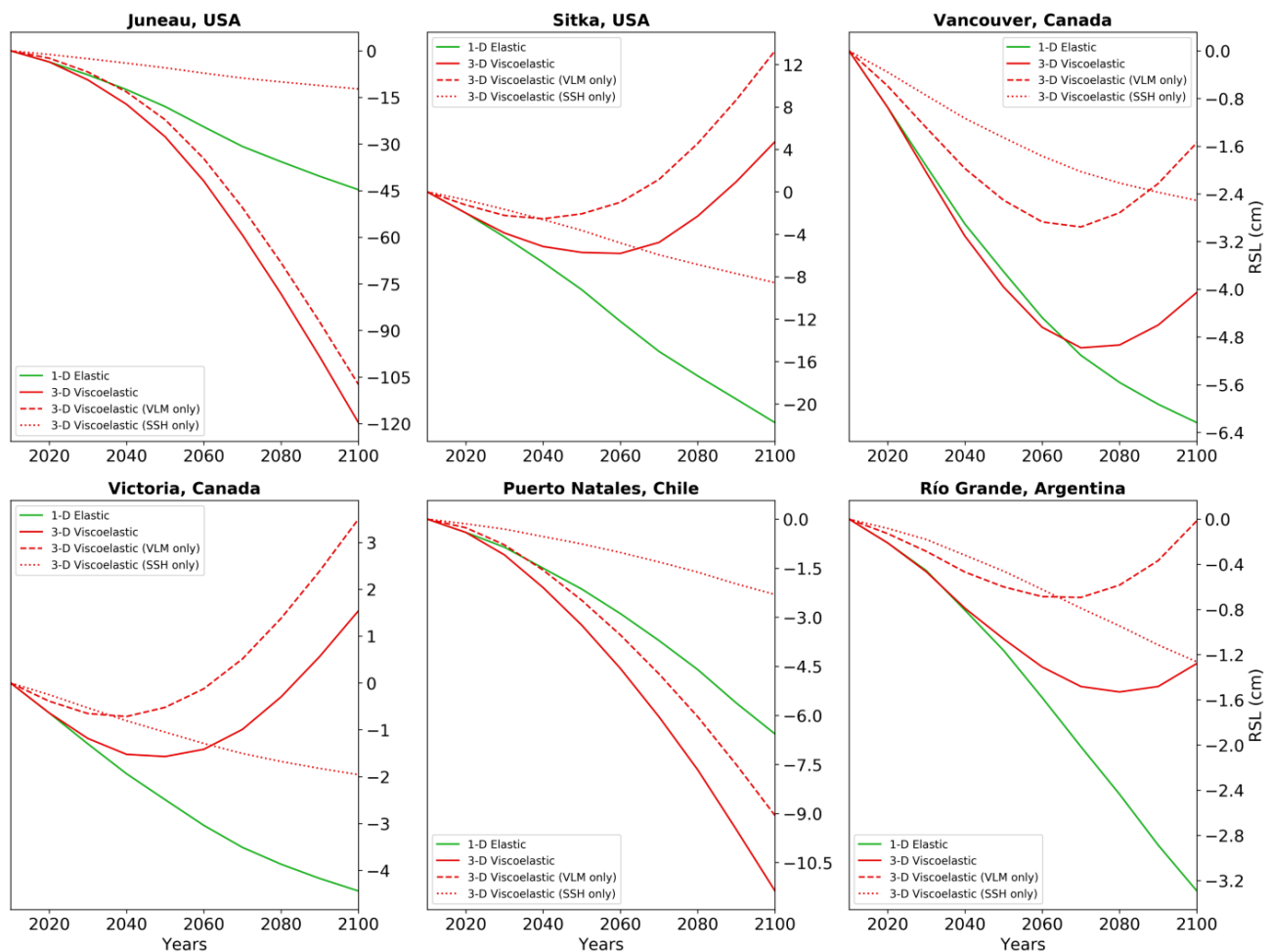


Figure 5. Calculated RSL curves showing the time variation of the spatial patterns in Fig. 4 at the locations indicated in Figs 1 and 4. The contributions of vertical land motion (VLM) and sea-surface height (SSH) change to RSL are also shown for the 3-D viscoelastic Earth model. As for Fig. 4, these results do not include the sea-level signal associated with ice mass changes from outside the respective RGI regions. **Why do you not show the VLM and SSH also for the elastic model?**