

1 **Calibration and analysis of the uncertainty in downscaling global land use and**
2 **land cover projections from GCAM using Demeter (v1.0.0)**

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15 **Abstract**

16 Demeter is a community spatial downscaling model that disaggregates land use and land cover
17 changes projected by integrated human-Earth system models. Demeter has not been intensively
18 calibrated, and we still lack a good knowledge about its sensitivity to key parameters and the parameter
19 uncertainties. We used long-term global satellite-based land cover records to calibrate key Demeter
20 parameters. The results identified the optimal parameter values and showed that the parameterization
21 substantially improved the model’s performance. The parameters of intensification ratio and selection
22 threshold were the most sensitive and needed to be carefully tuned, especially for regional applications.
23 Further, small parameter uncertainties after calibration can be inflated when propagated into future
24 scenarios, suggesting that users should consider the parameterization equifinality to better account for the
25 uncertainties in the Demeter downscaled products. Our study provides a key reference for Demeter users,
26 and ultimately contribute to reducing the uncertainties in Earth system model simulations.

27

28 **Key words:** Demeter; land use and land cover change; parameterization; human-Earth systems models

29

30 **1. Introduction**

31 Land Use and Land Cover Change (LULCC) represents one of the most important human impacts on
32 the Earth system (Hibbard et al., 2017). Besides its socioeconomic effects, LULCC is directly linked to
33 many natural land surface processes, such as land surface energy balance, carbon and water cycle (e.g.,
34 Piao *et al* 2007, Law *et al* 2018, Sleeter *et al* 2018, Pongratz *et al* 2006), and indirectly affects the climate
35 system (e.g., Dickinson and Kennedy 1992, Findell *et al* 2017, Costa and Foley 2000). Thus, LULCC has
36 been considered as a key process in simulating of Earth system dynamics, and LULCC inputs at
37 appropriate time steps and spatial resolutions are required to match the setup of the Earth System Models
38 (ESMs) and the nature of spatial heterogeneity of the Earth system processes (Brovkin et al., 2013;
39 Lawrence et al., 2016; Prestele et al., 2017).

40 While recent historical LULCC information can be obtained by ground investigation or satellite
41 remote sensing (Friedl et al., 2002; Hansen et al., 2000; Loveland et al., 2000; Zhang et al., 2003),
42 projections of future LULCC largely rely on mathematical models that bring socioeconomic and other
43 diverse sectoral information together in a coherent framework to simulate the interactions between natural
44 and human systems. However, these integrated models project LULCC at subregional level, i.e., the basic
45 spatial units that have uniform properties for every sector (e.g., agricultural, energy and water etc.),
46 typically ranging from a few hundred to millions of square kilometers (Edmonds et al., 2012). For
47 example, the GCAM model has been widely used to explore future societal and environmental scenarios
48 under different climate mitigation policies which provides LULCC projections at region-agroecological
49 or water basin level (Edmonds et al., 1997; Edmonds and Reilly, 1985; Kim et al., 2006). ESMs divide
50 the Earth surface into a number of grid cells and the forcing data have to be available at the same spatial
51 resolution to drive the ESMs (Taylor et al., 2012). Therefore, spatial downscaling of the subregional
52 LULCC becomes a critical step for linking models like GCAM and ESMs to investigate the effects of the
53 LULCC on the processes in the natural world, and further the interactions between the human and natural
54 systems (Hibbard and Janetos, 2013; Lawrence et al., 2012).

55 There has been a few spatial disaggregation studies for LULCC, e.g., the Global Land Use Model
56 (Hurt et al., 2011) and a dynamic global land use model (Meiyappan et al., 2014) with various
57 geographical and socioeconomic assumptions. In previous studies, we have developed a new simple and
58 efficient LULCC downscaling model, named Demeter (version 1.0.0), to bridge GCAM and ESMs (Le
59 Page et al., 2016; Vernon et al., 2018; West et al., 2014), and made it available online at
60 <http://doi.org/10.5281/zenodo.1214342> . Comparing to other models, Demeter makes minimal
61 assumptions of the socioeconomic impacts. Instead, it uses a few parameters to implicitly characterize the
62 spatial patterns of land use changes (See introductions in Section 2.1). Demeter has been successfully
63 applied at both global (Le Page et al., 2016) and regional (West et al., 2014) levels for downscaling
64 GCAM-projected land use and land cover changes, and has been further developed with an extensible

65 output module which streamlines producing specific output formats required by various ESMs (Vernon et
66 al., 2018). However, Demeter’s parameters (discussed in Section 2.1), which conclude many geographic
67 patterns of long-term land cover changes such as intensification and expansion, are difficult to determine
68 by either literature review or simple mathematical calculations. Therefore, Demeter’s parameter values
69 were empirically determined and a complete analysis on Demeter’s parametric sensitivity and
70 uncertainties as well as a rigorous model calibration has not been conducted to help minimize the
71 propagation of downscaling errors. In recent years, a growing number of long-term global remote-
72 sensing-based LULCC datasets are made available (e.g., the Land Cover project of the European Space
73 Agency Climate Change Initiative, MODIS Land Cover product collections 6), it becomes possible to use
74 these datasets to calibrate Demeter parameters. The major objective of this study is to develop a
75 framework for calibrating the key parameters of Demeter, testing and quantifying the parameter
76 sensitivities and uncertainties, and demonstrating how the parameter uncertainties would affect
77 downscaled products.

78

79 **2. Method**

80 *2.1 Demeter*

81 Demeter is a land use and land cover change downscaling model, which is designed to disaggregate
82 projections of land allocations generated by GCAM and other models. For example, GCAM projects land
83 cover areas in each of its spatial units (e.g., region-agro-ecological zones, region-AEZ) for each land
84 cover type, and Demeter uses gridded observational land cover data (e.g., satellite-based land cover
85 product) as the reference spatial distribution of land cover types and allocates the GCAM-projected land
86 area changes to grid level at a target spatial resolution, following some user-defined rules and spatial
87 constraints (Figure S1). Below we briefly summarize the key processes of Demeter, and the detailed
88 algorithms can be found in three earlier publications (Le Page et al., 2016; Vernon et al., 2018; West et
89 al., 2014).

90 Demeter first reconciles the land cover classes defined in the parent model and the reference dataset
91 to user-defined unified final land types (FLT). Downscaled land cover types will be presented in FLT.
92 For example, if Demeter reclassifies the 22 GCAM land cover types and the 16 International Geosphere-
93 Biosphere Programme (IGBP) land cover types from the reference dataset into 7 FLT (Forest, Shrub,
94 Grass, Crops, Urban and Sparse), the 7 FLT will be the land types represented in Demeter’s outputs by
95 default. Demeter then harmonizes the GCAM-projected land cover areas and the reference dataset at the
96 first time step (or ‘base year’) to make sure they are consistent with the GCAM spatial units and allocates
97 the projected land cover changes by intensification and extensification. Intensification is the process of
98 increasing a particular land cover in a grid cell where it already exists, while extensification creates new
99 land cover in grid cells where it does not yet exist but is in proximity to an existing allocation. The order

100 of transitions among land cover types is defined by “transition priorities” during the processes of
 101 intensification and extensification. A parameter (r , from 0 to 1) is defined as the ratio of intensification,
 102 and thus $1-r$ of the land cover change is for extensification. Proximal relationships are defined by spatial
 103 constraints that determine the probability that a grid cell may contain a particular land use or land cover
 104 class. The current Demeter setup includes three spatial constraints: kernel density (KD), soil workability
 105 (SW) and nutrient availability (NA). KD measures the probability density of a land cover type around a
 106 given grid cell, and SW and NA are normalized scalars (0~1) for agricultural suitability. For each land
 107 cover type and grid cell, KD is calculated by the spatial distance (D) at the runtime, and SW and NA are
 108 estimated from the Harmonized World Soil Database (HWSD, FAO/IIASA/ISRIC/ISSCAS/JRC, 2012).
 109 A suitability index (SI) from 0 to 1 is defined as the weighted-average of the three spatial constraints to
 110 assess how suitable a grid cell is to receive a land cover type:

$$SI = (w_K * KD + w_S * SW + w_N * NA) / (w_K + w_S + w_N) \quad (1)$$

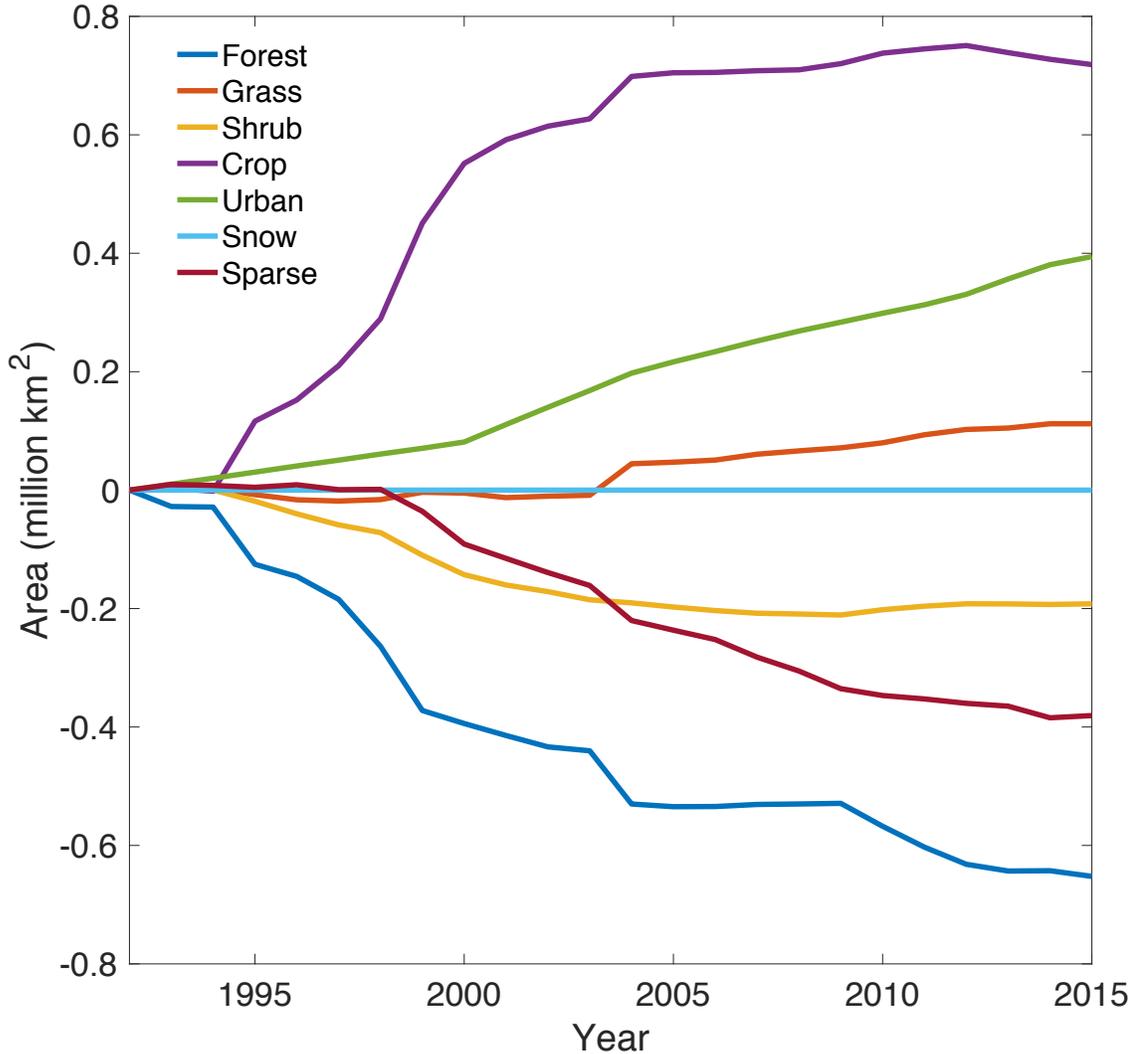
112 where w_K , w_S , and w_N are the weights for KD, SW and NA, respectively, and the sum of them is 1. In the
 113 process of extensification, Demeter ranks candidate grid cells based on their suitability indices and selects
 114 the most suitable candidate grid cells following a user-defined threshold percentage (τ) for extensification.
 115 In other words, τ determines the number of grid cells to be selected and used for the tentative and actual
 116 conversion of land cover types.

117
 118 Table 1. Transition priorities by analyzing the 24-year global land cover records from the Land Cover
 119 CCI project of the European Space Agency Climate Change Initiative. The rows and columns represent
 120 the origins and destinations of the transitions, respectively. The smaller numbers indicate higher transition
 121 priorities.

Final Land Types (origins)	Final Land Types (destinations)						
	Forest	Shrub	Grass	Crop	Urban	Snow	Sparse
Forest	0	2	3	1	4	5	6
Shrub	2	0	3	1	4	5	6
Grass	1	2	0	3	5	6	4
Crop	2	3	1	0	5	6	4
Urban	1	4	3	2	0	6	5
Snow	2	3	4	1	5	0	6
Sparse	2	3	4	1	5	6	0

122
 123 *2.2 Calibrate Demeter with historical land cover record and sensitivity analysis*

124 As indicated above, users should define a few parameters including the treatment order, the transition
125 priorities for allocating the land cover changes, the intensification ratio r , the selection threshold τ , the
126 radius for calculating kernel density D , and weights for the spatial constraints (w_K , w_S , and w_N), in order to
127 use Demeter for downscaling projected land cover change. These parameters were determined empirically
128 in previous studies. Here we calibrated these parameters for Demeter using a time series of global land
129 cover records from the Land Cover project of the European Space Agency Climate Change Initiative
130 (referred to as CCI-LC products hereafter). The CCI-LC products have been generated by critically
131 revisiting all algorithms required for the generation of a global land cover product from various Earth
132 Observation (EO) instruments, thus provide a globally consistent land cover record over two decades
133 (1992-2015). The CCI-LC products are available at 300 m spatial-resolution and annual time step and
134 classify the global land cover into 38 groups. We reclassified the CCI-LC products into the default 7
135 FLTs (Table S1) and resampled them into 0.25° resolution with the official software tools, following the
136 description of CCI-LC products in the user guide
137 (http://maps.elie.ucl.ac.be/CCI/viewer/download/ESACCI-LC-Ph2-PUGv2_2.0.pdf). Figure 1 shows
138 large interannual global changes for the 7 FLT areas, especially for the forests and croplands, which have
139 decreased and increased over 0.6 million km^2 over the past two decades, respectively. We used the
140 gridded 0.25° CCI-LC over the 24-year period as the observational data (below referred to “LC-grid-
141 obs”) and aggregated them into GCAM’s region-AEZ level to produce a synthetic GCAM-projected land
142 cover change (below referred to “LC-AEZ-syn”). In this way, we can apply Demeter to LC-AEZ-syn to
143 calibrate Demeter with the LC-grid-obs by tuning the parameters of Demeter.
144



145
 146 Figure 1. Interannual changes of global Final Land Types (FLT) areas over 1992-2015 relative
 147 to 1992, as indicated by the ESA CCI-LC product.

148 A preliminary sensitivity analysis of Demeter indicated that the downscaled results are not sensitive
 149 to treatment order and transition priorities (Le Page et al., 2016), thus we used the default treatment order,
 150 i.e., from least to greatest: Urban, Snow, Sparse, Crops, Forest, Grass, Shrub. We decided the transition
 151 priorities by sorting the probabilities of transitioning one FLT to another based on the 24-year CCI-LC
 152 record (Table 1). To calibrate the other six parameters (r , τ , w_K , w_S , w_N and D), we sampled their values at
 153 equal intervals (Table 2) and generated all possible combination (23,100 in total) for a Monte-Carlo
 154 ensemble Demeter downscaling experiment, using LC-AEZ-syn as the input. The Monte-Carlo
 155 experiment generated 23,100 sets of downscaled 0.25-degree global land use and land cover areas, which

156 were compared against LC-grid-obs to calculate their similarities to the observational data, ranked by
 157 their discrepancies from the least to greatest to determine the likelihood of the parameters. We calculated
 158 the discrepancies as the root mean square error (E_y) between the downscaled and observed land cover
 159 areas for each year:

$$E_y = \sqrt{\frac{1}{G} \frac{1}{L} \sum_g^G \sum_l^L (Ad_{y,l,g} - Ad_{o,l,g})^2} \quad (2)$$

161 and the average of the discrepancies over the years (E):

$$E = \frac{1}{Y} \sum_y^Y E_y \quad (3)$$

162 where g is the index for G grid cells over the globe ($G = 265,852$), l is the index for the L FLTs ($L = 8$), y
 163 is the index for Y years. We chose 1992, 2000, 2005, 2010 and 2015 to keep consistent with the GCAM
 164 time steps, thus $Y = 5$. $Ad_{y,l,g}$ and $Ad_{o,l,g}$ are the downscaled and observational land cover areas for grid
 165 cell g , FLT l and year y . The unit for E_y and E is km^2 .

167 To test the model sensitivity to these key parameters, we conducted a sensitivity analysis using the
 168 results from the Monte-Carlo experiment. The first-order and total-order Sobol sensitivity indices were
 169 used to identify the model sensitivity to each of the six parameters (Saltelli et al., 2004). Let θ_i denotes the
 170 i th parameter ($i=1, \dots, n$, here $n=6$), ε is the model outputs (i.e., the discrepancies between downscaled and
 171 observed land cover areas), the first-order Sobol index (S_i) is defined as:

$$S_i = \frac{Var[E(\varepsilon | \theta_i)]}{Var(\varepsilon)} \quad (4)$$

172 Here Var and E are the statistical variance and expectation. And the total-order Sobol index (S_{Ti}) is
 173 defined as the sum of sensitivity indices at any order involving parameter θ_i , where $S_{ijk\dots n}$ denotes the n th-
 174 order sensitivity index:
 175

$$S_{Ti} = S_i + \sum_{j=1, j \neq i}^n S_{ij} + \sum_{j,k=1, j,k \neq i}^n S_{ijk} + \dots + \sum_{j,k,\dots,n=1, j,k,\dots,n \neq i}^n S_{ijk\dots n} \quad (5)$$

176 The first-order Sobol index represents the contribution to the output variance of the main effect of θ_i ,
 177 therefore it measures the effect of varying θ_i alone; and the total-order Sobol index measures the
 178 contribution to output variance of θ_i and includes all variance caused by its interactions with other
 179 parameters. Larger Sobol indices indicate higher parameter sensitivities.
 180
 181
 182
 183

184 Table 2. Key parameters, and their sampling range and steps for calibration in this study.

Name	Definition	Min	Max	Sampling step
w_N	Weight of soil nutrient availability for calculating suitability index	0	1	0.2
w_S	Weight of soil workability for calculating suitability index	0	1	0.2
w_K	Weight of kernel density for calculating suitability index	0	1	0.2
r	Intensification ratio	0	1	0.1
τ	Selection threshold	0	1	0.1
D	Kernel radius	10	100	10

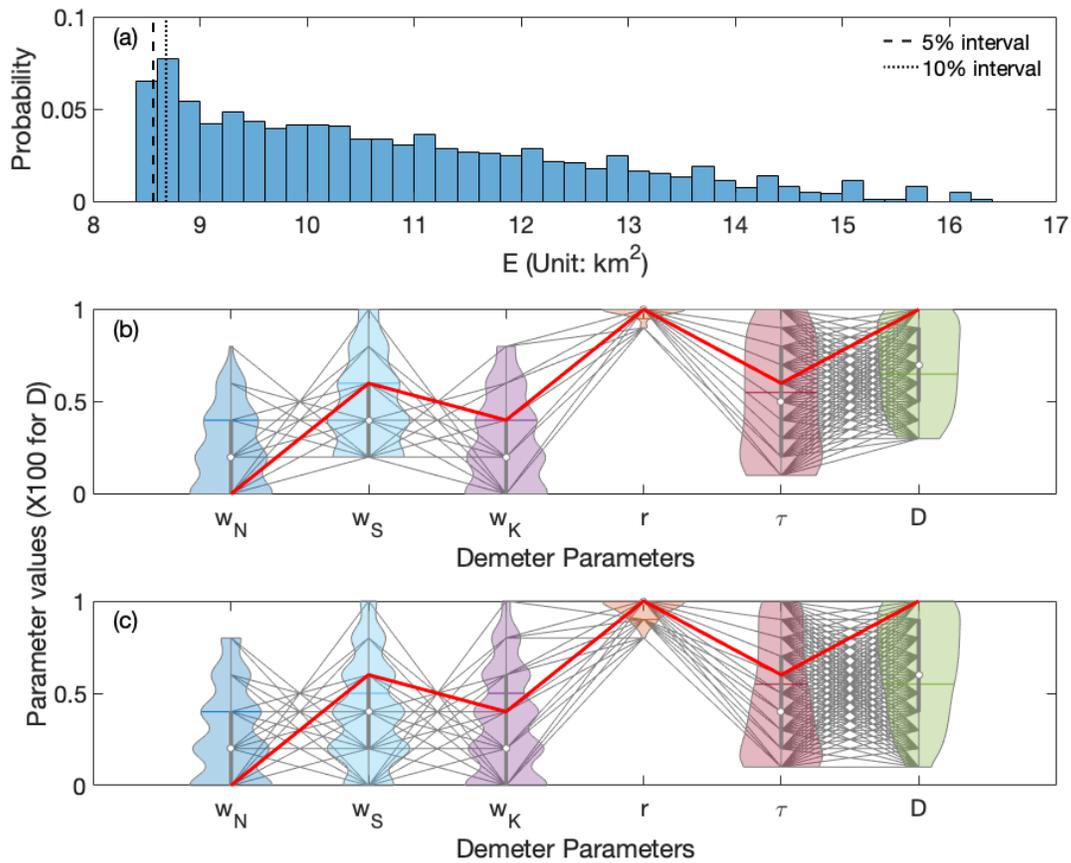
185
 186 *2.3 Propagate the parameter uncertainties to GCAM LULCC downscaling*
 187 We selected parameter combinations which produced the smallest 5% E_s based on their rankings
 188 from the Monte-Carlo experiment, and used them as ‘acceptable’ parameters to represent the parameter
 189 uncertainties after calibration. We used Demeter with these parameters to downscale the GCAM-
 190 projected LULCC at 5-year time step from 2005 to 2100 under a reference scenario to examine the
 191 uncertainties of land cover areas for each FLT to demonstrate how different the downscaled LULCC can
 192 be induced by the uncertain parameters. The reference scenario is a business-as-usual case with no
 193 explicit climate mitigation efforts that reaches a higher radiative forcing level of over 7 W m^{-2} in 2100.
 194 We only saved the downscaling results in 2005, 2010, 2050 and 2100 considering the size of the output
 195 files and computational cost. Finally, we calculated the standard deviation across the downscaled land
 196 cover areas for each FLT driven by different parameter combinations, which indicates the parameter-
 197 induced model uncertainties.

198
 199 **3. Results**

200 *3.1 Parameter estimation and sensitivity*

201 The Monte-Carlo Demeter experiment driven by the 23,100 ensemble parameter sets produced
 202 diverse downscaled LULCC realizations. As shown in Figure 2a, the disagreements between the
 203 downscaled FLT fraction and the reference record, measured by the average root mean square error (E ,

204 Equation 3) for all the FLT and grid cells over the five years (1992, 2000, 2005, 2010 and 2015), are
 205 mainly distributed between 8 and 17 km² (about 1%-3% of the area of a 0.25-degree grid cell).

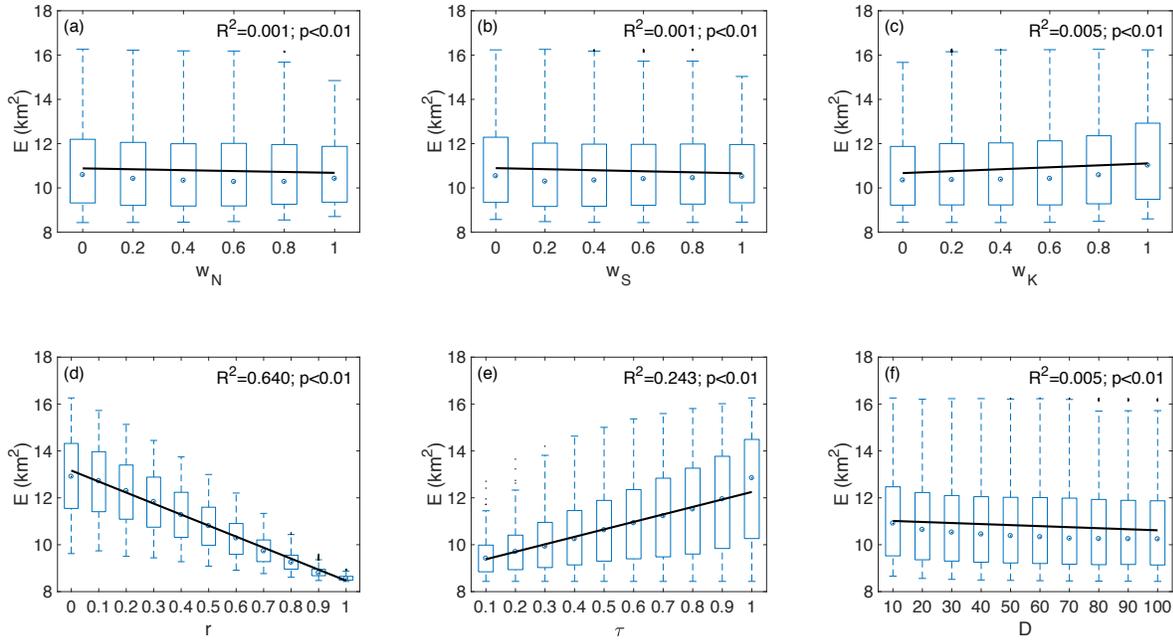


206

207 Figure 2. (a) Histogram of the E s, i.e., the global average discrepancies between the downscaled
 208 and observed land cover areas with the 23,100 ensemble parameter sets; the vertical dashed line
 209 in (a) shows the interval of the ‘acceptable’ 5% parameters, as described in Section 2.3; (b) the
 210 probability density of each of the ‘acceptable’ 5% parameters, as shown by the violin plots; the
 211 black lines across the six parameters show all the ‘acceptable’ 5% parameter sets, and the red
 212 line indicates the global optimal parameter values; the box plots and horizontal bar inside the
 213 violin plots indicate the interquartile ranges and the mean of the parameter values, respectively.
 214 (c) same as (b) but shows the ‘best’ 10% parameter sets. Note that the values of D were divided
 215 by 100 for the purpose of illustration in (b) and (c).

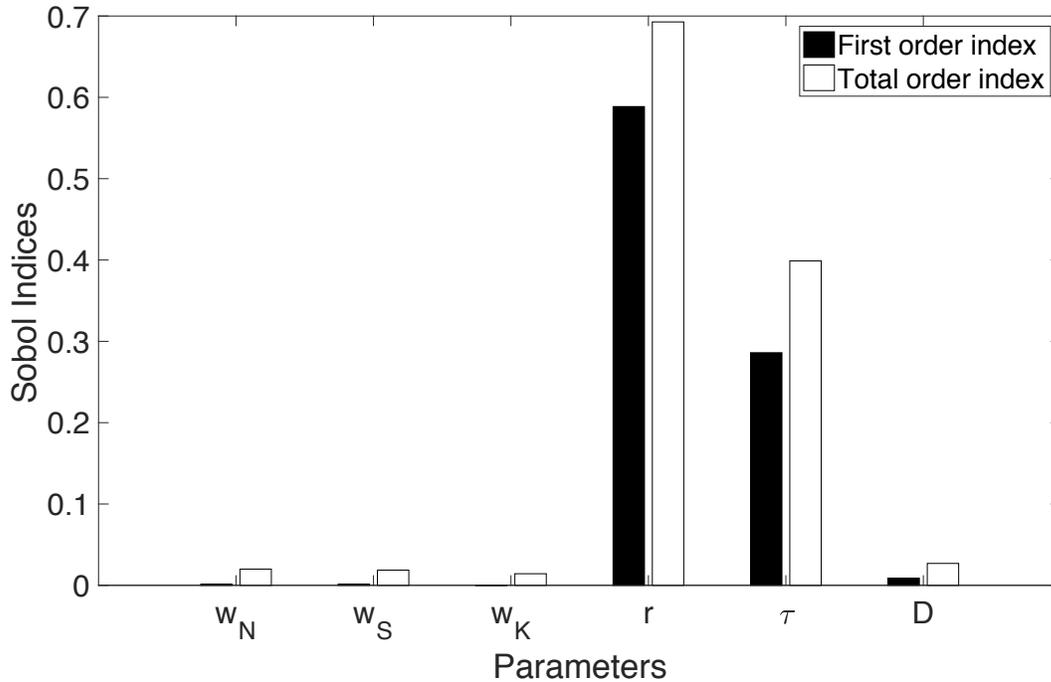
216 Figure 3 shows the relationship between the values of the six parameters and their corresponding E s,
 217 resulted from the Monte-Carlo experiment. We found that the E s are significantly correlated to all the six
 218 parameters ($p < 0.01$). The intensification ratio (r) has the strongest linear correlation with the E s

219 ($R^2=0.64$), followed by the selection threshold (τ) ($R^2 = 0.24$). Overall, the parameters w_K and τ are
 220 positively correlated with E_s (positive slopes of the trendlines), while w_N, w_S, r and D hold negative
 221 correlations, indicating that smaller w_K and τ , and larger w_N, w_S, r and D are associated with smaller E_s .



222
 223 Figure 3. Relationships between the six Demeter parameters and the global average
 224 discrepancies between the downscaled and observed land cover areas (E_s) resulted from the
 225 Monte-Carlo ensemble experiment. Box plots shows distributions of the E_s and the solid lines
 226 show the linear trends.

227 Figure 4 shows the first-order and total-order Sobol indices calculated with the parameter ensemble
 228 and the associated E_s . As indicated by the first-order Sobol indices, the intensification ratio r directly
 229 contributes about 59% to the variability of the E_s , followed by the selection threshold τ and kernel radius
 230 D , which directly contribute 29% and 1% to the variability of the E_s . The other parameters (w_N, w_S and
 231 w_K) have little direct contributions to the E variability. The total-order Sobol indices showed similar order
 232 of parameter importance. r and its interactions with other parameters contributed about 70% of the E
 233 variability, τ contributed about 40%, D contributed about 3%, and w_N, w_S and w_K contributed 2%
 234 respectively. It is clear that the downscaling error is most sensitive to the intensification ratio, followed by
 235 the selection threshold, but not sensitive to the kernel radius and the weighting factors of the spatial
 236 constraints.



237

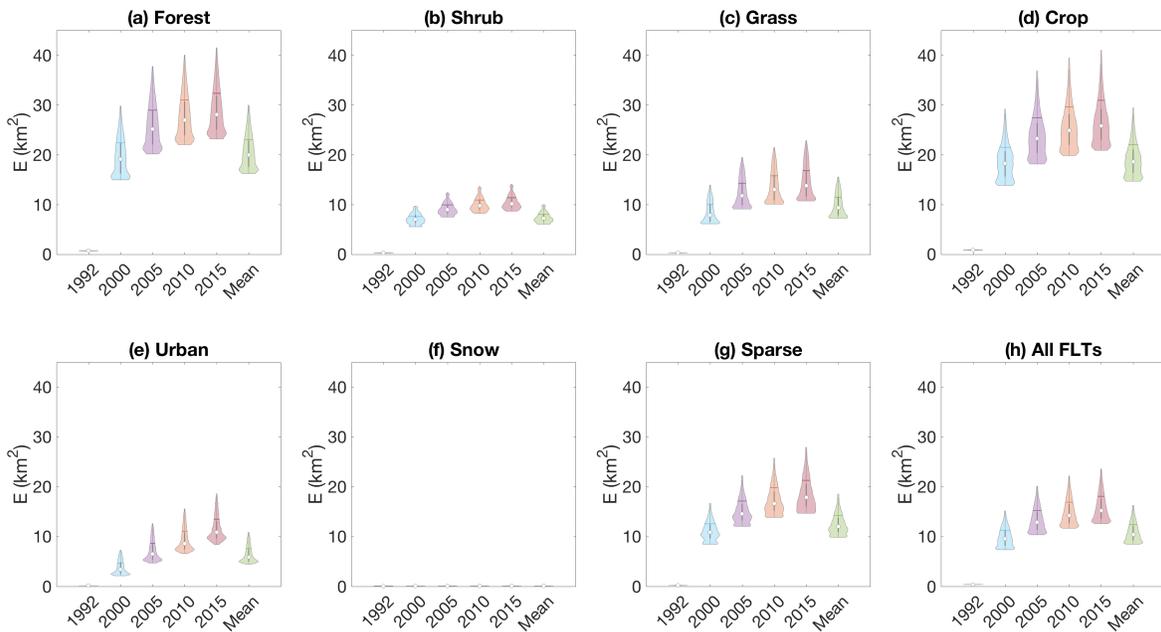
238 Figure 4. Sobol sensitivity indices for the six Demeter parameters. Higher indices indicate higher
 239 sensitivities.

240 We identified the ‘best’ parameters, which are associated with the lowest E , and marked them as the
 241 red line in Figure 2b. We also selected ‘acceptable’ parameters that have E s lower than 5% quantile in
 242 Figure 2a (hereafter referred to as ‘top 5% parameters’) and thus have the similar performance as the
 243 ‘best’ parameters (differences of $E < 1\%$), and used them to represent the uncertainty of the parameters
 244 shown as the probability density distributions in Figure 2b. The best w_N , w_S , w_K , r , τ and D are 0, 0.6, 0.4,
 245 1, 0.6 and 100, respectively. All the parameters are constrained with the calibration comparing to their
 246 uniform prior distributions. The intensification ratio r has been constrained into a small range (0.9-1.0 and
 247 mostly 1.0) from 0-1.0. Constraining on the other parameters are relatively weaker: w_N , w_S , and w_K have
 248 been narrowed to the ranges of 0-0.8, 0.2-1.0, and 0-0.8, and primarily distributed in 0-0.4, 0.2-0.6 and 0-
 249 0.4 (the first and third quantiles), respectively; τ and D have been constrained into the range of 0.2-1.0
 250 and 30-100 with the first and third quantiles being 0.2-0.8 and 40-90, respectively. This analysis again
 251 indicates that r is the most sensitive parameter, therefore its posterior distribution can be significantly
 252 narrowed through the calibration. In addition, we also selected the ‘acceptable’ parameters that have E s
 253 lower than 10% quantile (top 10% parameters), as shown in Figure 2a and 2c. Similar distribution of top
 254 10% parameters are found as that of the top 5% parameters, with some small extension on the ranges of
 255 5% parameters.

256

257 3.2 Performance of Demeter in downscaling LULCC

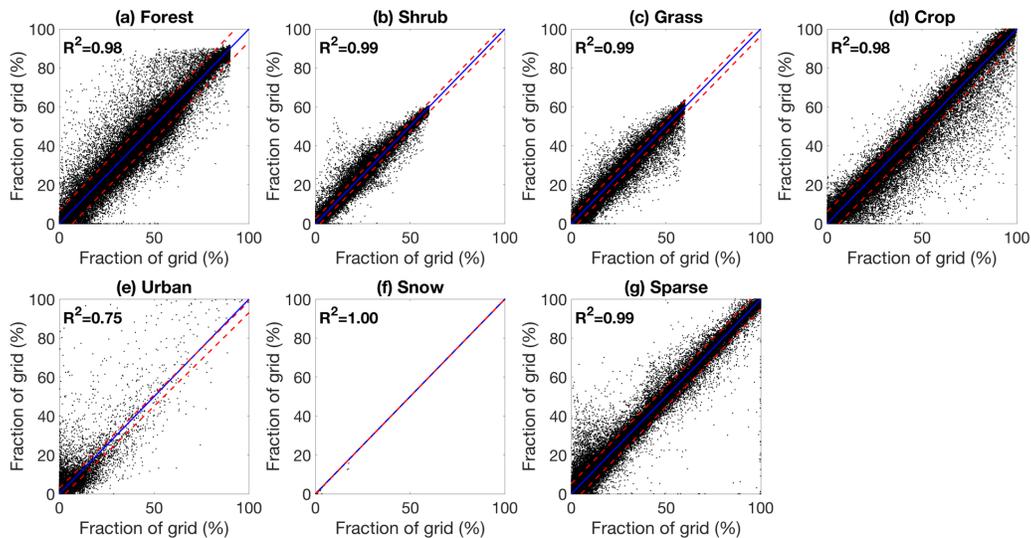
258 Demeter generally performs well in downscaling the synthetic land use and land cover change with
 259 small disagreements with the reference data. For all FLT, the disagreements between the downscaled
 260 FLT fraction and the reference record in 1992 (i.e., E_{1992} in Equation 2), are close to zero since we used it
 261 as the harmonization year. The disagreements in 2000 (E_{2000}) are mainly distributed in a range between 5
 262 and 15 km² (about 1%-2% of a 0.25-degree grid cell), with the median about 10 km² and the mean
 263 slightly above 12 km² (Figure 5h). The disagreements increase over years at a rate of about 1 km² per 5-
 264 year time step and reach 13-24 km² (median: 15 km²; mean: 18 km²) in 2015. Overall, the average
 265 disagreements over the five years (E) mainly distributed in 8-17 km² (also shown in Figure 2a), with the
 266 median of about 10 km² and the mean of about 12 km².



267
 268 Figure 5. Possibility densities for the E_s between downscaled and observational Final Land Type
 269 areas for 1992, 2000, 2005, 2010, 2015 and the mean of the five time-steps. The box plots and
 270 horizontal bar inside the violin plots indicate the interquartile ranges and the mean of the
 271 parameter values, respectively. Note that the E_s for Snow are close to 0 thus not visible in the
 272 figure.

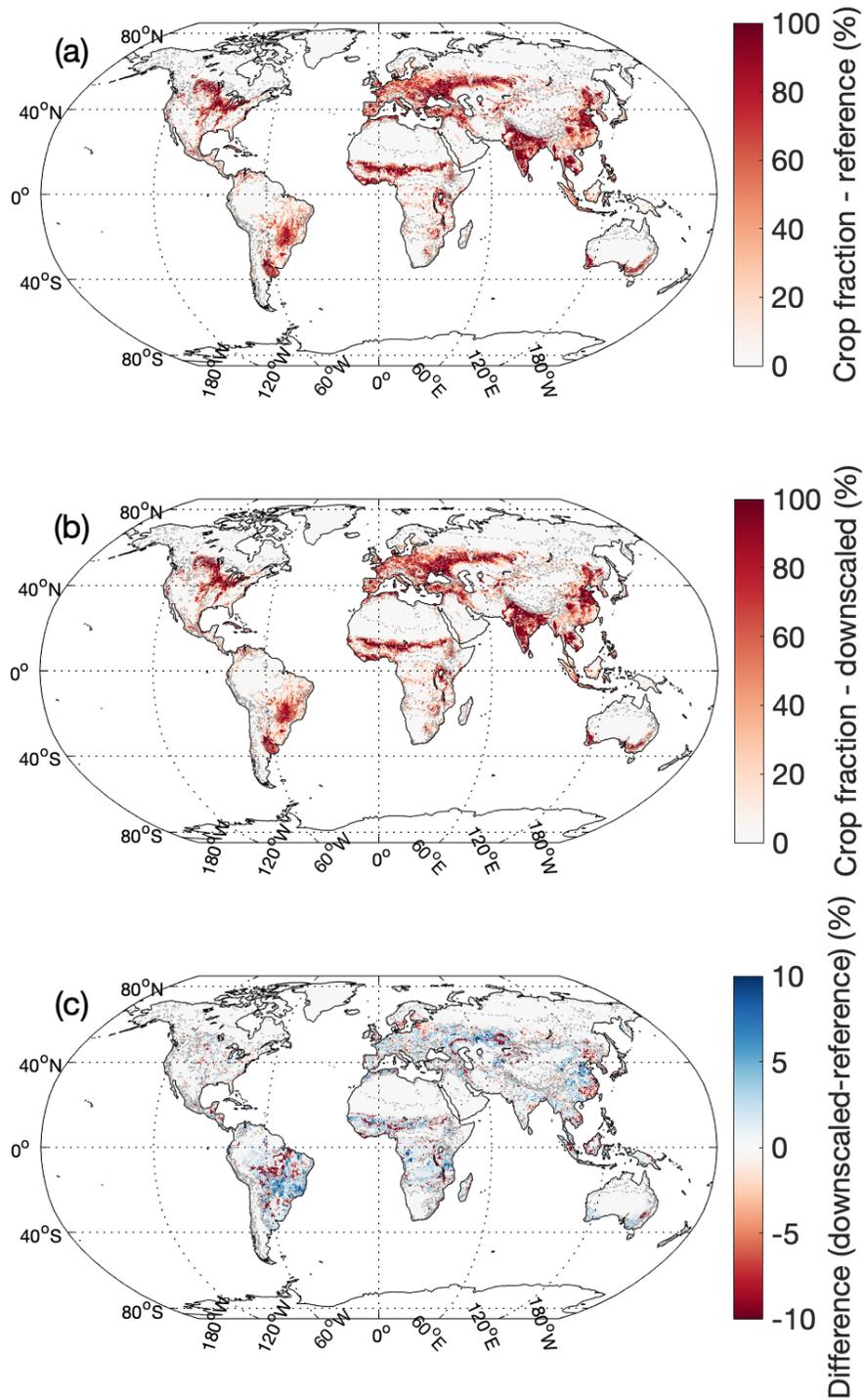
273
 274 The errors for each of the FLT follow the same increasing trend over the years. Forest and crop have
 275 the largest disagreements between the downscaled and reference distributions with the errors are
 276 primarily located in the range of 20-40 km² in average over the five time steps (Figure 5a,d). The errors
 277 for sparse lands are relatively smaller, which mainly fall into the range of 10-20 km² (Figure 5g),

278 followed by grass, shrub and urban, with the errors are mainly distributed in 0-10 km² averagely over the
279 five years. Errors for snow is near zero since there was little areal change for this FLT in the CCI-LC
280 record (Figure 1) and little LULCC allocation was needed in the downscaling process over the years.



281
282 Figure 6. Comparison between the observed and downscaled Final Land Type with optimal
283 parameters over the 265,852 0.25-degree grid cells in 2015. The blue solid lines show the 1:1
284 line, and the red dashed lines show the 95% confidence intervals.

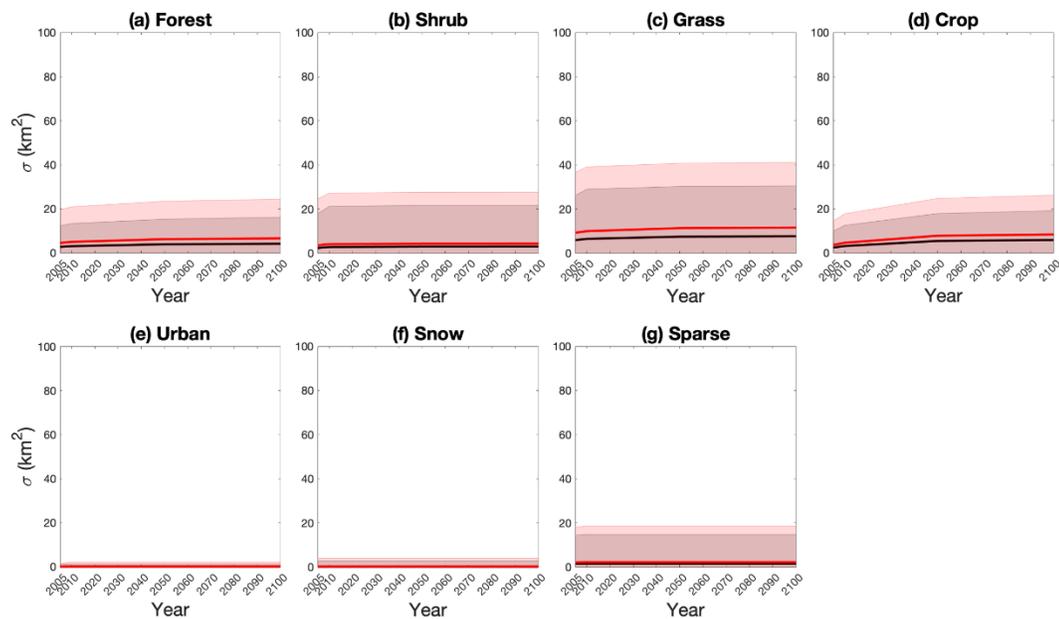
285 Figure 6 shows the comparison between reference gridded CCI-LC FLT_s and the downscaled FLT_s
286 driven by the best parameters (see Section 3.1) among the 265,852 0.25-degree grid cells in 2015. Except
287 for urban, the downscaled land cover of other FLT_s match the reference record very well (all R² are above
288 0.98). The R² is 1 for snow due to little change of snow and ice area in the CCI-LC record. Figure 7
289 demonstrates the spatial distribution of FLT fraction from the reference data and best downscaled results,
290 together with their differences, using crop as an example. We find that the downscaled results have
291 successfully reproduced the spatial pattern of crops from the reference data, and similar conclusions can
292 be drawn for other FLT_s (see Figure S2-S6; figure for Snow was not shown because of little change for
293 this FLT). However, misallocation of the land cover change takes places in most region-AEZs, especially
294 where LULCC were significant (e.g., Brazil, Eastern China, temperate Africa and Northern Euroasia;
295 Figure 7 and S1-S5) over the study years, likely due to the application of improper global ratio of
296 intensification. For example, the Northern China plain has experienced extensive urbanization by
297 converting a large area of cropland into urbans during the past few decades (Liu et al., 2010). However,
298 since the calibrated intensification ratio is high (Figure 2), Demeter tends to underestimate the urban
299 expansion and thus overestimate cropland area at where should be urbanized. Similarly, cropland has
300 been largely expanded and thus applying a high intensification ratio could not capture such changes.



303 Figure 7. Spatial pattern of the observed and downscaled Crop density (measured by percentage
 304 fraction of the grid cell), and their differences in 2015. The grey dot-lines show the boundaries of
 305 the GCAM region-AEZs.

306 3.3 Uncertainty propagation

307 While applying the ‘acceptable’ parameters (top 5% and 10%) in downscaling GCAM projections of
308 LULCC under the reference scenario, we found that these well-constrained parameters induced
309 considerable uncertainties in the downscaled results. For each grid cell, we calculated the standard
310 deviation (σ) of the downscaled land cover areas with different parameters for each FLT. Figure 8 shows
311 the mean σ of the 265,852 0.25-degree grid cells over the globe for 2005, 2010, 2050 and 2100, as well as
312 the spatial variability of σ (calculated as the standard deviation over the grid cells and shown as the
313 shaded area in Figure 8). As shown by the grey lines and shades in Figure 8, the uncertainty of top 5%
314 parameters has minor effect on downscaled Urban and Snow areas, since GCAM projected little areal
315 changes of urban and snow. Downscaled sparse areas were slightly affected by the choice of parameters,
316 indicated by small mean σ (about 2 km² per grid cell). However, the other FLTs, including Forest, Shrub,
317 Grass and Crop have larger σ s, which also showed an increasing trend over time. The global mean σ for
318 Forest and Shrub reached about 3 to 4 km² per grid cell and about 6 to 8 km² for Grass and Crop in 2100.
319 The spatial variability of σ was also larger for these FLTs, for example, the standard deviation of σ
320 reached over 15 km² per grid cell in 2100 for Crop, and the maximum σ can be over 350 km² per grid cell
321 in some grid cells (Figure S7). Similar results can be found by using the top 10% parameters, but with
322 slightly higher magnitudes (red lines and shaded areas in Figure 8 and Figure S8).



323
324 Figure 8. The Mean (shown as the solid lines) and standard deviations (σ , shown as the shaded
325 area) for the downscaled Final Land Type (FLT) areas, when propagating the parameter
326 uncertainties into the GCAM-projected land use and land cover change downscaling in the 21st
327 century. The black and red colors represent using the top 5% and 10% parameters, respectively.

328 4. Discussion

329 To date, there has been only a handful of methods for downscaling projected global land use and land
330 cover change. For example, Oskins *et al* (2016) fitted a statistical model relating coarse-scaled spatial
331 patterns in land cover classes to finer-scaled land cover and other explaining variables. Many more
332 studies used complex land use modeling approach (e.g., Houet *et al* 2017, Oskins *et al* 2016, Meiyappan
333 *et al* 2014, Hurtt *et al* 2011, Souty *et al* 2012) that combines a variety of socioeconomic processes to
334 provide global scale land use allocations. Our results demonstrated that Demeter is an effective tool for
335 downscaling global land use and land cover change, although it adapts a relatively simpler approach.
336 However, choices of parameter values are critically important for a simple model, since it is possible that
337 some complicated processes are simplified to be represented by a single parameter. Although an
338 uncalibrated Demeter can lead to noticeable errors and uncertainties in downscaled land cover areas, our
339 results have shown the effectiveness of the calibration efforts in minimizing the downscaling errors and
340 constraining the uncertainties.

341 A central purpose of our study is to making suggestions for setting up parameters for Demeter's
342 global applications, shown as the global optimal values in Figure 2. Interestingly, we found that the
343 parameters of intensification ratio (r) and selection threshold (τ) strongly affected the downscaled results,
344 while the weights of the spatial constraints and kernel radius showed small impacts on the results. This
345 result indicates that the selected spatial constraints (soil workability and nutrient availability) and spatial
346 autocorrelation (measured by kernel density) provide loose constrains on the land allocation in the
347 downscaling process, therefore the users should focus more on the quality of other parameters such as r
348 and τ to which the model is more sensitive. In addition, the intensification ratio has been strictly
349 constrained to a range close to 1.0, suggesting that the intensification of land cover, especially cropland,
350 may be the major contributor to the global land use and land cover change, thus spatial constraints on
351 extensification are not very effective. We also noticed that the optimal weight for soil nutrient availability
352 for calculating the suitability indices is zero (Figure 2) and the model. A possible reason is that the soil
353 nutrient availability has similar spatial distribution as the cropland in ESA-CCI data, thus provides little
354 additional information in constraining the downscaling processes (Figure S10). This result suggests that
355 the users could ignore the input of soil nutrient availability if it is not available or difficult to collect, and
356 the quantification of the downscaling uncertainty is not required.

357 There has been a number of numerical methods for model calibration, such as gradient methods
358 (Ypma, 1995), evolutionary algorithms (Ashlock, 2006), and data assimilation techniques (Kalnay, 2002).
359 Our calibration method is relatively simpler, and the sampling steps are relatively coarse. As a result, it is
360 possible that the calibrated parameters can be further improved with a more rigorous calibration strategy,
361 although these biases should be small since the sampling bins are narrow and the sensitive parameters are
362 well constrained (Figure 2). However, our method has a few advantages for this particular global land use

363 and land cover change downscaling model calibration problem. First, we sampled the whole parameter
364 space thus our Monte-Carlo downscaling experiments can well represent the parameter uncertainties.
365 Second, the other methods mentioned above typically adjust model parameters and run the model
366 iteratively to find the parameters to hit the local or global minimum cost function value (Chong and Zak,
367 2013), and thus can be very time consuming due to the size of the datasets and the difficulty of algorithm
368 parallelization. The Monte-Carlo ensemble runs of Demeter in our method can be easily parallelized and
369 thus is computationally efficient. Finally, the saved downscaled results from the global Monte-Carlo
370 downscaling experiment can be reused for regional applications. Our study provided an optimal set of
371 Demeter parameters. It is worth noting that these parameters are optimized to minimize the average
372 discrepancies between the downscaled and historically observed land cover areas at the global scale, thus
373 they may need to be recalibrated when Demeter is applied to a particular region. For example, the best
374 estimate of the intensification ratio is 1 for a global downscaling experiment, probably due to that
375 intensification is a more common phenomena than extensification during the past land use and land cover
376 change in the past two decades as recorded by the ESA-CCI data. However, this high intensification ratio
377 for Crop may be more realistic for the regions with long-term agricultural history (e.g., India), while it
378 should become lower for the United States (US) where cropland extensification rapidly happened in the
379 past century. We extracted the grid cells in the conterminous US (grid cells between 25° N and 50° N, and
380 125° W and 65° W) and India (grid cells between 7° N and 33° N, and 68° E and 98° E), and used them
381 together with the same method as the global calibration to determine the optimal parameters for the US
382 and India, which clearly showed that the intensification ratio remained 1 for India, but moved towards
383 lower values for the US (Figure S9). Therefore, we recommend future efforts on examining regional
384 parameterization should be made for Demeter's applications at specific regional/AEZ levels. Since some
385 of the key parameters have clear physical definition (e.g., the intensification ratio), while the global
386 optimal values could be used as a starting point, it would be helpful to review the local historical land use
387 change to infer these parameters when applying Demeter to a specific region.

388 In addition, although the downscaled urban land use can capture most of the variability in reality, it is
389 clear that Demeter's performance for urban is not as good as that for other land cover types (Figure 6). On
390 the other hand, accurate projection of the spatial extent and pattern of urbanization is getting more
391 important for better understanding its environmental, ecological and socioeconomic impacts in such an
392 era of rapid urbanization (Georgescu et al., 2012; Jones et al., 1990; Merckx et al., 2018; Zhang et al.,
393 2018). Thus, a key future effort should be made for improving the downscaling accuracy of urban land
394 use. The relative larger errors could be either due to the limited consideration of complex urbanization
395 processes and the lack of specific parameterization of the urban land cover type. While incorporating
396 better representation of urbanization in Demeter can be more complicated, it is possible to improve the
397 model performance by further parameterizing the model with more historical urban data. For example,

398 global satellite-observed nightlights have been used for mapping urban area (Elvidge et al., 2009; Li and
399 Zhou, 2017b; Zhou et al., 2014) and producing a global record of annual urban dynamics (1992-2013) (Li
400 and Zhou, 2017a), which will be particularly useful for the future calibration of Demeter on urban
401 dynamics.

402 Model calibration usually can provide several sets of parameters to allow the calibrated model to give
403 similar results, which is called equifinality (Beven and Freer, 2001). As a result, the calibrated parameters
404 become another source of uncertainty in model-simulated results. The equifinality also exists in our
405 calibrations. We have observed noticeable growing uncertainties in downscaled land cover areas while
406 propagating the parameter uncertainties into the Demeter downscaling practices with GCAM projected
407 LULCC in the 21st century. Therefore, while calibration can remarkably reduce the uncertainty of the
408 parameters, it may be better to use sets of constrained parameters rather than a single set of ‘best’
409 parameters in the practice of Demeter, for the purpose of accounting for the parameter uncertainty and
410 providing more reliable land use and land cover change downscaling. Moreover, it is worth noting that the
411 calibrated parameters are tuned for FLTs, which we believe have covered most land cover types and are
412 directly useful in most cases. When the users need to consider more FLTs in their global applications, the
413 optimal values introduced in this study can be used as a starting point for further tuning.

414

415 **5. Conclusions**

416 We developed a Monte-Carlo ensemble experiment for Demeter, a land use and land cover change
417 downscaling model of GCAM, analyzed the model’s sensitivity to its key parameters, and calibrated the
418 parameters to minimize the mismatch between the model-downscaled and satellite-observed land use and
419 land cover change in the past two decades. We identified the optimal parameter values for global
420 applications of Demeter, and showed that the parameterization of Demeter substantially improved the
421 model’s performance in downscaling global land use and land cover change. The intensification ratio and
422 selection threshold turned out to be the most sensitive parameters, thus need to be carefully tuned,
423 especially when Demeter is used for regional applications. Further, the small uncertainty of parameters
424 after calibration can result in considerably larger uncertainties in the results when propagating them into
425 the practice of downscaling GCAM projections, suggesting that Demeter users consider the
426 parameterization equifinality to better account the uncertainties in the Demeter downscaled land use and
427 land cover changes.

428

429

430 **Code Availability**

431 The source code of GCAM and Demeter is available at <https://github.com/JGCRI/gcam-core>

432 and <https://github.com/IMMM-SFA/demeter>. The scripts for performing the calibration and analysis are
433 available at https://drive.google.com/open?id=1qNzh4eKgVcO_BjG2RjAw33whqxSMH8wm.

434

435 **Data Availability**

436 The ESA-CCI data was downloaded from <https://www.esa-landcover-cci.org/>. Other data are available at
437 https://drive.google.com/open?id=1qNzh4eKgVcO_BjG2RjAw33whqxSMH8wm.

438

439 **Author contribution**

440 M.C. conceived the study and all the authors contributed to design the study. M.C. lead the data
441 acquisition and performed the experiment and analysis with technical assistance from C.V.; M.C. wrote
442 the manuscript with the inputs from all the coauthors.

443

444 **Competing interests**

445 The authors declare that they have no conflict of interest.

446

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