

Interactive comment on “Autonomous underwater vehicle based marine multi-component self-potential method: observation scheme and navigational correction” by Zhongmin Zhu et al.

Lev Eppelbaum (Editor)

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Dear Reviewers and Authors,

Thank you for the careful revision of this paper.

After the comprehensive revision, this original paper finally accepted for publication.

Lev Eppelbaum Assoc. Editor

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